2 Introduction to perturbation methods

2.1 What are perturbation methods?

Perturbation methods are methods which rely on there being a dimensionless parameter in the problem that is relatively small: $\varepsilon \ll 1$. The most common example you may have seen before is that of high-Reynolds number fluid mechanics, in which a viscous boundary layer is found close to a solid surface. Note that in this case the standard physical parameter Re is large: our small parameter is $\varepsilon = Re^{-1}$.

2.2 A real research example

This comes from my own research². I will not present the equations or the working here: but the problem in question is the stability of a polymer extrusion flow. The parameter varied is wavelength: and for both very long waves (wavenumber $k \ll 1$) and very short waves $(k^{-1} \ll 1)$ the system is much simplified. The long-wave case, in particular, gives very good insight into the physics of the problem.

If we look at the plot of growth rate of the instability against wavenumber (inverse wavelength):



we can see good agreement between the perturbation method solutions (the dotted lines) and the numerical calculations (solid curve): this kind of agreement gives confidence in the numerics in the middle region where perturbation methods can't help.

3 Regular perturbation expansions

We're all familiar with the principle of the Taylor expansion: for an analytic function f(x), we can expand close to a point x = a as:

$$f(a + \varepsilon) = f(a) + \varepsilon f'(a) + \frac{1}{2}\varepsilon^2 f''(a) + \cdots$$

For general functions f(x) there are many ways this expansion can fail, including lack of convergence of the series, or simply an inability of the series to capture the behaviour of the function; but the paradigm of the expansion in which a

²H J Wilson & J M Rallison. J. Non-Newtonian Fluid Mech., 72, 237–251, (1997)

small change to x makes a small change to f(x) is a powerful one, and the basis of regular perturbation expansions.

The basic principle and practice of the regular perturbation expansion is:

- 1. Set $\varepsilon = 0$ and solve the resulting system (solution f_0 for definiteness)
- 2. Perturb the system by allowing ε to be nonzero (but small in some sense).
- 3. Formulate the solution to the new, perturbed system as a series

$$f_0 + \varepsilon f_1 + \varepsilon^2 f_2 + \cdots$$

4. Expand the governing equations as a series in ε , collecting terms with equal powers of ε ; solve them in turn as far as the solution is required.

3.1 Example differential equation

Suppose we are trying to solve the following differential equation in $x \ge 0$:

$$\frac{\mathrm{d}f(x)}{\mathrm{d}x} + f(x) - \varepsilon f^2(x) = 0, \qquad f(0) = 2.$$
(1)

Ignore the fact that we could have solved this equation directly! We'll use it as a model for more complex examples.

We look first at $\varepsilon = 0$:

$$\frac{\mathrm{d}f(x)}{\mathrm{d}x} + f(x) = 0, \qquad f(0) = 2, \qquad \Longrightarrow \qquad f(x) = 2e^{-x}.$$

Now we follow our system and set

$$f = 2e^{-x} + \varepsilon f_1(x) + \varepsilon^2 f_2(x) + \varepsilon^3 f_3(x) + \cdots$$

where in order to satisfy the initial condition f(0) = 2, we will have $f_1(0) = f_2(0) = f_3(0) = \cdots = 0$. Substituting into (1) gives

and we can collect powers of ε :

$$\begin{array}{rcl} \varepsilon^0 & : & -2e^{-x} + 2e^{-x} & = 0 \\ \varepsilon^1 & : & f_1'(x) + f_1(x) - 4e^{-2x} & = 0 \\ \varepsilon^2 & : & f_2'(x) + f_2(x) - 4e^{-x}f_1(x) & = 0 \\ \varepsilon^3 & : & f_3'(x) + f_3(x) - f_1^2(x) - 4e^{-x}f_2(x) & = 0 \end{array}$$

The order ε^0 (or 1) equation is satisfied automatically. Now we simply solve at each order, applying the boundary conditions as we go along.

Order ε terms.

 $f'_1(x) + f_1(x) = 4e^{-2x} \implies f_1(x) = -4e^{-2x} + c_1e^{-x}$ and the boundary condition $f_1(0) = 0$ gives $c_1 = 4$:

$$f_1(x) = 4(e^{-x} - e^{-2x}).$$

Order ε^2 terms.

The equation becomes

$$f_2'(x) + f_2(x) = 4e^{-x}f_1(x) \implies f_2'(x) + f_2(x) = 16e^{-x}(e^{-x} - e^{-2x})$$

with solution

$$f_2(x) = 8(-2e^{-2x} + e^{-3x}) + c_2e^{-x}$$

and the boundary condition $f_2(0) = 0$ gives $c_2 = 8$:

$$f_2(x) = 8(e^{-x} - 2e^{-2x} + e^{-3x}).$$

Order ε^3 terms.

The equation is $f'_{3}(x) + f_{3}(x) - f^{2}_{1}(x) - 4e^{-x}f_{2}(x) = 0$ which becomes

$$f_3'(x) + f_3(x) = 48(e^{-2x} - 2e^{-3x} + e^{-4x}).$$

The solution to this equation is

$$f_3(x) = 16(-3e^{-2x} + 3e^{-3x} - e^{-4x}) + c_3e^{-x}.$$

Applying the boundary condition $f_3(0) = 0$ gives $c_3 = 16$ so

$$f_3(x) = 16(e^{-x} - 3e^{-2x} + 3e^{-3x} - e^{-4x}).$$

The solution we have found is:

$$f(x) = 2e^{-x} + 4\varepsilon(e^{-x} - e^{-2x}) + 8\varepsilon^2(e^{-x} - 2e^{-2x} + e^{-3x}) + 16\varepsilon^3(e^{-x} - 3e^{-2x} + 3e^{-3x} - e^{-4x}) + \cdots$$

This is an example of a case where carrying out a perturbation expansion gives us an insight into the full solution. Notice that, for the terms we have calculated,

$$f_n(x) = 2^{n+1} e^{-x} (1 - e^{-x})^n,$$

suggesting a guessed full solution

$$f(x) = \sum_{n=0}^{\infty} \varepsilon^n 2^{n+1} e^{-x} (1 - e^{-x})^n = 2e^{-x} \sum_{n=0}^{\infty} [2\varepsilon(1 - e^{-x})]^n = \frac{2e^{-x}}{1 - 2\varepsilon(1 - e^{-x})}.$$

Having guessed a solution, of course, verifying it is straightforward: this is indeed the correct solution to the ODE of equation (1).

3.2 Example eigenvalue problem

We will find the first-order perturbations of the eigenvalues of the differential equation

$$y'' + \lambda y + \varepsilon y^2 = 0$$

in $0 < x < \pi$, with boundary conditions $y(0) = y(\pi) = 0$. [Exercise: repeat this with the final term as εy (easy) or εy^3 (harder).] First we look at the case $\varepsilon = 0$:

$$y'' + \lambda y = 0$$

This has possible solutions:

$$\begin{split} \lambda &< 0 \qquad y = A \cosh\left[x\sqrt{-\lambda}\right] + B \sinh\left[x\sqrt{-\lambda}\right] \\ \lambda &= 0 \qquad y = Ax + B \\ \lambda &> 0 \qquad y = A \cos\left[x\sqrt{\lambda}\right] + B \sin\left[x\sqrt{\lambda}\right] \end{split}$$

The first two solutions can't satisfy both boundary conditions. The third must have A = 0 to satisfy the condition y(0) = 0, and the second boundary condition leaves us with

$$B\sin\left[\pi\sqrt{\lambda}\right] = 0 \implies \lambda = m^2, \ m = 1, 2, \dots$$

Now we return to the full problem, posing regular expansions in both y and λ :

$$y = \sin mx + \varepsilon y_1 + \cdots$$

$$\lambda = m^2 + \varepsilon \lambda_1 + \cdots$$

Substituting in, we obtain for the differential equation:

$$\begin{array}{rcl} -m^2 \sin mx &+ m^2 \sin mx &= 0\\ \varepsilon y_1'' &+ \varepsilon m^2 y_1 + \varepsilon \lambda_1 \sin mx &+ \varepsilon \sin^2 mx &= 0 \end{array}$$

As we would expect, the order 1 equation is already satisfied, along with the boundary conditions.

Order ε

The ODE at order ε becomes

$$y_1'' + m^2 y_1 = -\lambda_1 \sin mx - \sin^2 mx = -\lambda_1 \sin mx + \frac{1}{2} \cos 2mx - \frac{1}{2}.$$

We expect a solution of the form

$$y_1 = A\sin mx + B\cos mx + Cx\cos mx + D\cos 2mx + E$$

and substituting this form back in to the left hand side gives us

$$-2Cm\sin mx - 3m^2D\cos 2mx + Em^2 = -\lambda_1\sin mx + \frac{1}{2}\cos 2mx - \frac{1}{2}$$

which fixes $C = \lambda_1/2m$, $D = -1/6m^2$, $E = -1/2m^2$. The solution is

$$y_1 = A\sin mx + B\cos mx + \frac{\lambda_1}{2m}x\cos mx - \frac{1}{2m^2} - \frac{1}{6m^2}\cos 2mx.$$

Now we apply the boundary conditions to determine the eigenvalue: y(0) = 0 gives

$$0 = B - \frac{1}{2m^2} - \frac{1}{6m^2} \qquad B = \frac{2}{3m^2}$$

and then the condition $y(\pi) = 0$ becomes:

$$0 = \frac{2}{3m^2}(-1)^m + \frac{\lambda_1}{2m}\pi(-1)^m - \frac{1}{2m^2} - \frac{1}{6m^2}$$

which simplifies to determine λ_1 :

$$\lambda_1 = \frac{4}{3m\pi} [(-1)^m - 1] = \frac{-8}{3m\pi} \begin{cases} 0 & m \text{ even} \\ 1 & m \text{ odd} \end{cases}$$

Thus the eigenvalues become

$$\lambda = 1 - \frac{8\varepsilon}{3\pi}, 4, 9 - \frac{8\varepsilon}{9\pi}, 16, 25 - \frac{8\varepsilon}{15\pi}, \cdots$$

3.3 Warning signs

As I mentioned earlier, the Taylor series model of function behaviour does not always work. The same is true for model systems: and a regular perturbation expansion will not always capture the behaviour of your system. Here are a few of the possible warning signs that things might be going wrong:

One of the powers of ε produces an insoluble equation

By this I don't mean a differential equation with no analytic solution: that is just bad luck. Rather I mean an equation of the form $x_1 + 1 - x_1 = 0$ which cannot be satisfied by any value of x_1 .

The equation at $\varepsilon = 0$ doesn't give the right number of solutions

An *n*th order ODE should have *n* solutions. If the equation produced by setting $\varepsilon = 0$ has less solutions then this method will not give all the possible solutions to the full equation. This happens when the coefficient of the highest derivative is zero when $\varepsilon = 0$. Equally, for a PDE, if the solution you find at $\varepsilon = 0$ cannot satisfy all your boundary conditions, then a regular expansion will not be enough.

The coefficients of ε can grow without bound

In the case of an expansion $f(x) = f_0(x) + \varepsilon f_1(x) + \varepsilon^2 f_2(x) + \cdots$, the series may not be valid for some values of x if some or all of the $f_i(x)$ become very large. Say, for example, that $f_2(x) \to \infty$ while $f_1(x)$ remains finite. Then $\varepsilon f_1(x)$ is no longer strictly larger than $\varepsilon^2 f_2(x)$ and who knows what even larger terms we may have neglected...