

MATHEMATICS 1302 (Applied Mathematics 2)  
YEAR 2008–2009, TERM 2

PRACTICE FINAL EXAM

**Note:** The actual exam will have 6 questions, of which the best 4 will count. Here I am giving you just 5 questions.

1. A body is projected vertically upwards from the surface of the earth with initial velocity  $v_0$ . Neglect air resistance, but do *not* make the approximation that  $g$  is constant.
  - (a) Describe qualitatively the possible motions in as much detail as possible (e.g. explaining the asymptotic behavior as  $t \rightarrow +\infty$ ). You will need to distinguish three cases:  $v_0 < v_{escape}$ ,  $v_0 = v_{escape}$  and  $v_0 > v_{escape}$ . Compute  $v_{escape}$  in terms of  $G$ ,  $M_{earth}$  and  $R_{earth}$ .
  - (b) Find the distance from the center of the earth as a function of time for the case  $v_0 = v_{escape}$ .
2.
  - (a) Write the unit vectors  $\hat{\mathbf{e}}_r$  and  $\hat{\mathbf{e}}_\theta$  of plane polar coordinates in terms of the Cartesian unit vectors  $\hat{\mathbf{e}}_x$  and  $\hat{\mathbf{e}}_y$  and the coordinates  $r$  and  $\theta$ .
  - (b) Consider a particle moving with polar coordinates  $(r(t), \theta(t))$ . Using your result from part (a) — or by any other valid method — show that

$$\begin{aligned}\frac{d}{dt} \hat{\mathbf{e}}_r &= \dot{\theta} \hat{\mathbf{e}}_\theta \\ \frac{d}{dt} \hat{\mathbf{e}}_\theta &= -\dot{\theta} \hat{\mathbf{e}}_r\end{aligned}$$

where  $\dot{\theta}$  denotes  $d\theta/dt$ .

- (c) Write the position vector  $\mathbf{r}$ , the velocity vector  $\mathbf{v} = d\mathbf{r}/dt$ , the acceleration vector  $\mathbf{a} = d^2\mathbf{r}/dt^2$  and the “jerk” vector  $\mathbf{j} = d^3\mathbf{r}/dt^3$  as linear combinations of  $\hat{\mathbf{e}}_r$  and  $\hat{\mathbf{e}}_\theta$  with coefficients that involve  $r$ ,  $\theta$  and their time derivatives.
3. A particle slides frictionlessly under the influence of gravity on the inverted parabola  $y = -\frac{x^2}{2a}$ .
    - (a) Write the horizontal ( $x$ ) and vertical ( $y$ ) components of Newton’s equations of motion.
    - (b) Eliminate the constraint and the constraint force to get a differential equation for  $x(t)$  alone.

- (c) Write the equation of energy conservation for the motion  $x(t)$ .
- (d) Differentiate the energy-conservation equation and show that it agrees with the equation of motion derived in part (b).
- (e) Write  $t(x)$  in the form of a definite integral, being careful about initial conditions. But don't bother to evaluate the integral.
- (f) Assume that the particle starts from  $x = 0$  with initial velocity  $v_0$ . Show that there exist three values of  $v_0$  for which the subsequent motion is  $x(t) = v_0 t$ , and find those values.
4. A simple pendulum of length  $\ell$ , whose bob has a mass  $m$ , is attached to a support moving vertically upward with constant acceleration  $a$ . Let  $\theta$  be the angle of the pendulum relative to the vertical.
- (a) Write the Cartesian coordinates  $x(t)$  and  $y(t)$  of the pendulum bob in terms of the angle  $\theta(t)$ .
- (b) Write the horizontal ( $x$ ) and vertical ( $y$ ) components of Newton's equations of motion.
- (c) Eliminate the constraint and the constraint force to get a differential equation for  $\theta(t)$  alone.
- (d) Find the frequency of small oscillations around  $\theta = 0$ .
- (e) Is energy conserved? Why or why not?
5. A smooth thin wire is bent into the shape  $z = f(x)$ , where  $f$  is some specified function satisfying  $f(x) = f(-x)$ . This wire is then made to rotate with angular velocity  $\omega$  about the  $z$  axis [i.e. about the point  $x = 0$  on the wire]; here the  $+z$  direction is of course oriented upwards. A bead of mass  $m$  then slides frictionlessly on the wire under the influence of gravity. Using cylindrical coordinates  $(\rho, \varphi, z)$ , discuss the motion of the bead, as follows. Write your answers in terms of the function  $f$  and its derivatives.
- (a) Write the  $\rho$ ,  $\varphi$  and  $z$  components of Newton's equations of motion for the bead. Your equations will contain two unknown constraint forces.
- (b) Use the equations of constraint to eliminate all reference to  $\varphi$ ,  $z$ , and their time derivatives as well as to the constraint forces. That is, you should obtain a differential equation for  $\rho$  alone.
- (c) Fix some value  $\rho_0$ . What value of  $\omega$  will allow the bead to remain at rest at  $\rho = \rho_0$ ?
- (d) If  $\omega$  is chosen as in part (c), under what conditions is the solution  $\rho = \rho_0$  stable? When it is stable, find the frequency of small oscillations about the solution  $\rho = \rho_0$ .