

MATHEMATICS 0054 (Analytical Dynamics)  
YEAR 2021–2022, TERM 2

PROBLEM SET #5

This problem set is due at the *beginning* of the *noon* lecture on Monday 7 March.

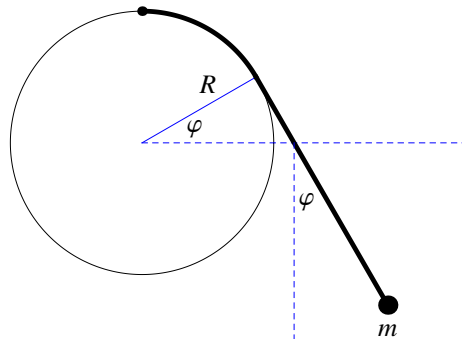
**Topics:** Lagrangian approach to mechanics.

**Reading:**

- Gregory, *Classical Mechanics*, Chapter 12 (handout).
- Handout #11: The Lagrangian approach to mechanics.

1. [You have seen this problem before!]

A pendulum is constructed by attaching a mass  $m$  to an unstretchable string of length  $l$ . The upper end of the string is connected to the uppermost point on a fixed vertical disk of radius  $R$ , as shown in the diagram. Assume that  $l > (\pi/2)R$ .



Obtain the Lagrangian of this system in terms of the generalized coordinate  $\varphi$ , and derive the exact equation of motion. [You already did last week almost all the work needed for this.]

*Remark:* When we considered this problem before, we got the equation of motion from energy conservation. Note that in this case of a conservative system with *one* degree of freedom, the Lagrangian method is no simpler than the energy-conservation method: after all, if we can write  $L = T - V$ , then we can also write  $E = T + V$ ! The Lagrangian method becomes advantageous when dealing with constrained systems with  $n \geq 2$  degrees of freedom: for these systems, energy conservation alone does *not* suffice to give the full equations of motion (we need  $n$  independent equations, but energy conservation only gives one).

2. A bead slides under the influence of gravity on the frictionless interior surface of the paraboloid of revolution  $z = (x^2 + y^2)/2a = r^2/2a$ . Use cylindrical coordinates  $(r, \varphi, z)$ .

Let us first analyze this problem by Newtonian methods:

- (a) Write the  $r$ ,  $\varphi$  and  $z$  components of Newton's equations of motion for the bead. Your equations will of course contain an unknown constraint force.
- (b) Find the equations of motion for the bead coordinates  $(r, \varphi)$ , by eliminating  $z$  and the constraint force.
- (c) Find two conserved quantities. [*Hint:* In what directions do the forces point? What, in addition to energy, will therefore be conserved?]
- (d) Find a closed equation of motion for  $r$  alone. One of the conserved quantities will appear as a parameter in your equation. [*Hint:* Recall the solution of the central-force problem.]
- (e) Find the speed  $v_0$  at which the bead will move in a horizontal circle of radius  $r_0$ .
- (f) Find the frequency of small radial oscillations around the circular motion found in part (e).

Now let's try it by Lagrangian methods:

- (g) Find the Lagrangian and obtain the equations of motion for the bead coordinates  $(r, \varphi)$ . Does it agree with what you found previously by Newtonian methods?
- (h) Show that the coordinate  $\varphi$  is cyclic, and hence that the conjugate momentum  $p_\varphi$  is conserved. Does this agree with what you found previously by Newtonian methods? What is the physical significance of  $p_\varphi$ ?

3. A smooth thin wire is bent into the shape of a parabola,  $z = x^2/2a$ , and is made to rotate with a constant angular velocity  $\omega$  about the  $z$  axis [i.e. about the point  $x = 0$  on the wire]; here the  $+z$  direction is of course oriented upwards. A bead of mass  $m$  then slides frictionlessly on the wire under the influence of gravity. Use cylindrical coordinates  $(r, \varphi, z)$ .

Let us first analyze this problem by Newtonian methods:

- (a) Write the  $r$ ,  $\varphi$  and  $z$  components of Newton's equations of motion for the bead. Your equations will contain two unknown constraint forces.
- (b) Use the equations of constraint to eliminate all reference to  $\varphi$ ,  $z$ , and their time derivatives as well as to the constraint forces. That is, you should obtain a differential equation for  $r$  alone.
- (c) Show that the total mechanical energy  $E$  of the bead is *not* conserved, and that the constraint force does work at a rate precisely  $dE/dt$ .
- (d) Show that the equation of motion found in part (b) can be integrated once by the usual trick of multiplying it by  $\dot{r}$ . What is the relation between this result and part (c)?

- (e) Integrate the equation of motion once more to get an “explicit” expression for  $t$  as a function of  $r$  (albeit in terms of an ugly integral).

Now let’s try it by Lagrangian methods:

- (f) Write the Lagrangian in terms of the single degree of freedom  $r$ , and derive the equation of motion. Does it agree with what you found previously by Newtonian methods?

Note that this problem is a nontrivial test of the Lagrangian formalism, as it involves a time-dependent constraint. In particular, the constraint force does work, so that the total energy  $E$  is *not* conserved. Nevertheless, the Lagrangian formalism gives the correct equation of motion, without fuss.