

# BCI-TVR: Brain computer interface training with virtual reality

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## Introduction

- Brain computer interfaces and their users are often trained in very calm environments
- This environment does not simulate the real world environments that the BCI users will operate in
- When BCI trained on data produced in a calm environment is used in real world settings, the performance of the machine learning classifier degrades

## Our Aims

- Use virtual reality to simulate a real world environment
- We hypothesise that this will improve the generalisability of the classifier i.e. better performance across different environments
- Deploy the system on a BCI controlled wheelchair

## EEG VR headset



Figure 1: EEG VR headset combination

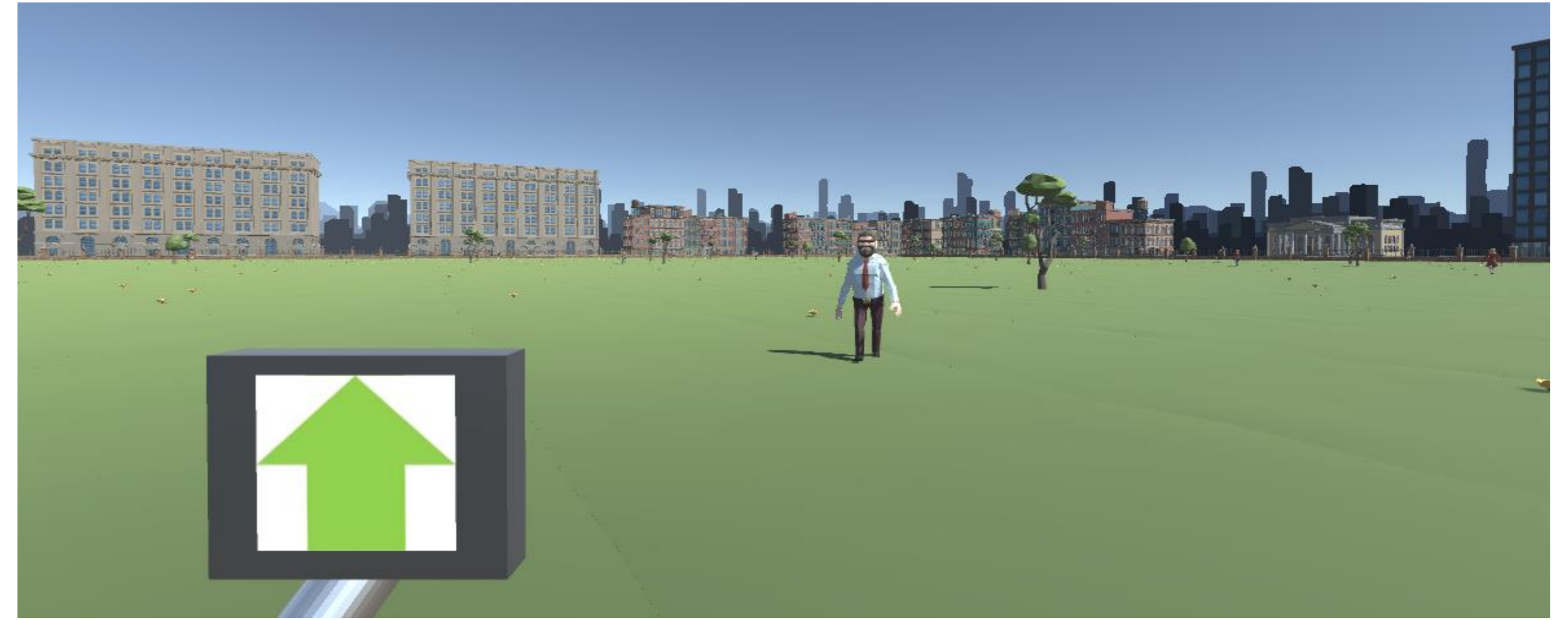


Figure 3: view from VR headset of virtual environment



Figure 4: User using a prototype simulation

## EEG Electrodes

- 16 electrodes placed in 10-20 positions:
- 512Hz sampling rate

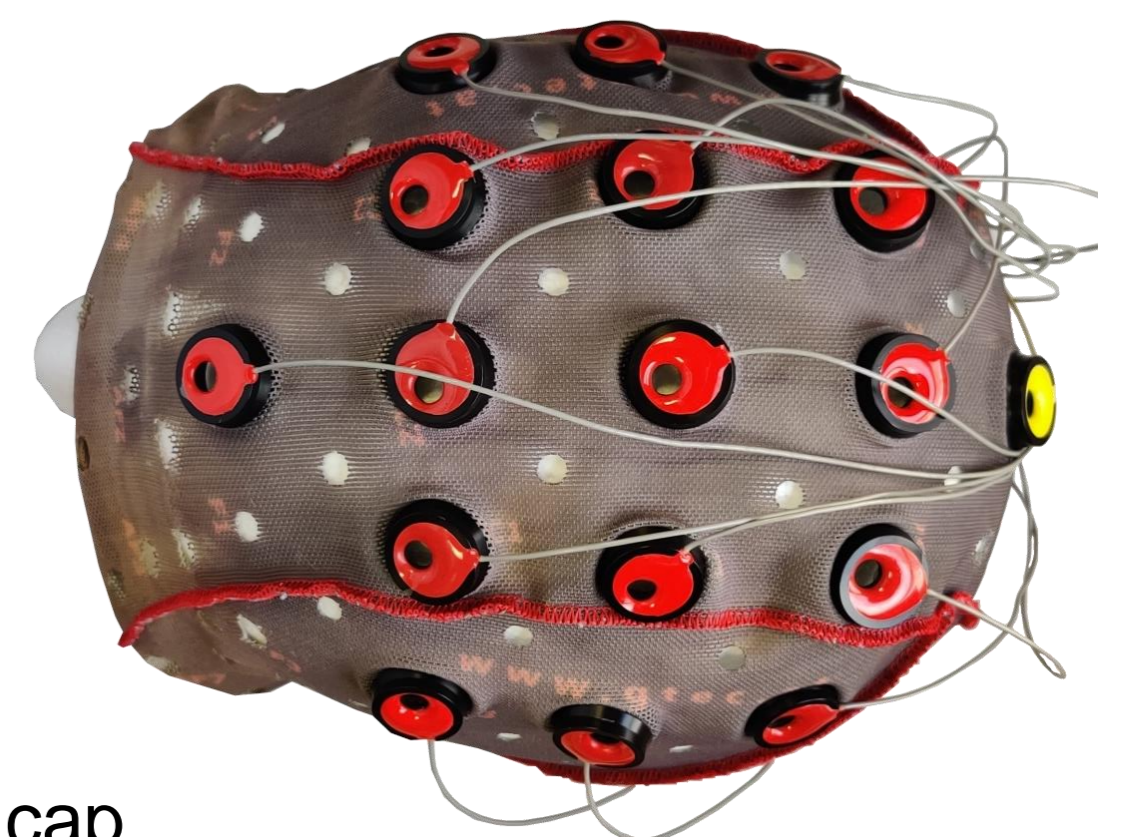


Figure 5: Birds eye view of EEG cap

## Shared control

- Our Wheelchair makes use of a system known as shared control, where the assistive device that the BCI controls also has an influence on the final action taken
- The wheelchair is equipped with an array of ultrasonic sensors

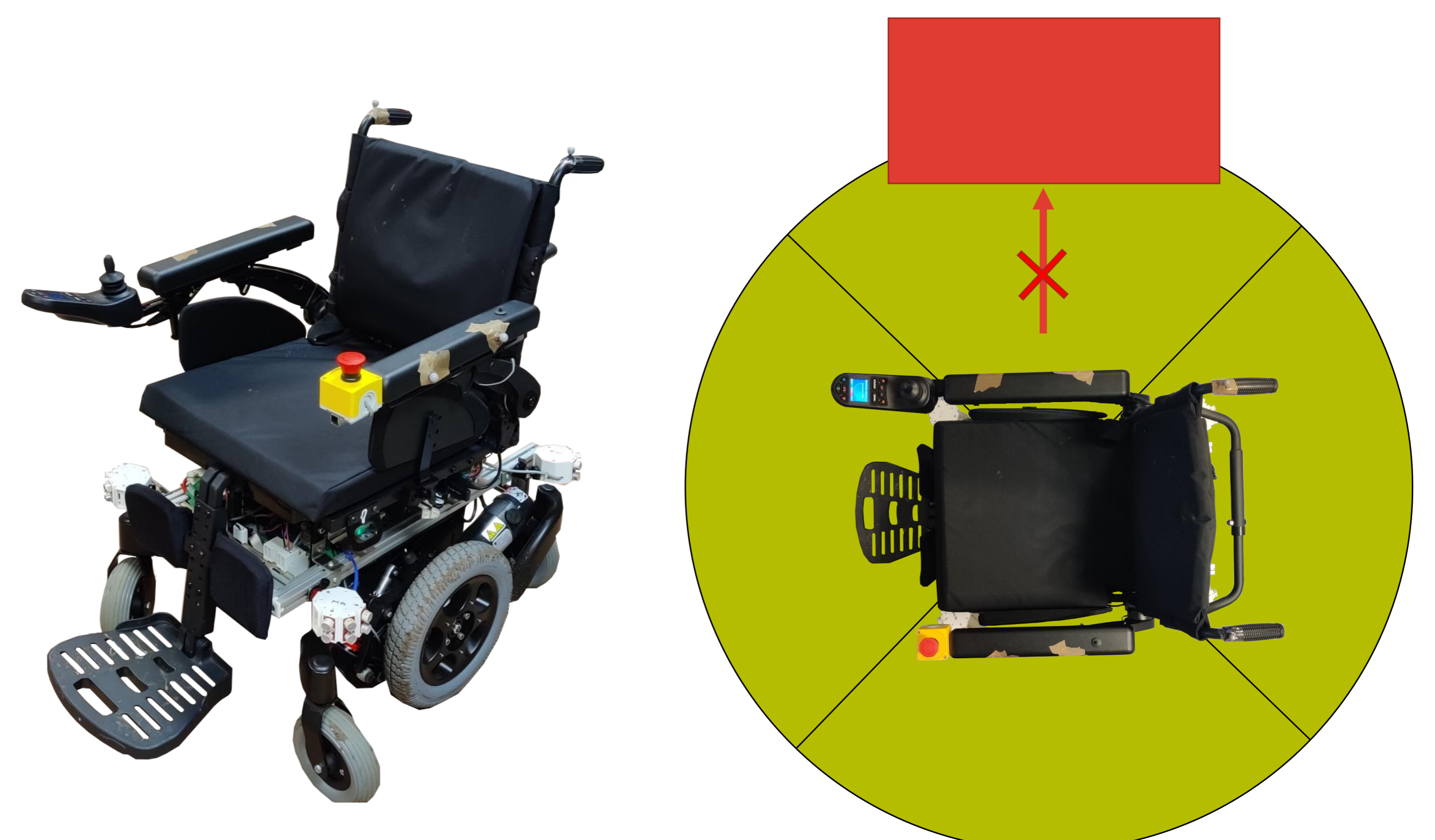


Figure 6: shared control wheelchair

## Control through Motor Imagery

- We can detect changes in the EEG power spectrum when we imagine movement of the hands and feet

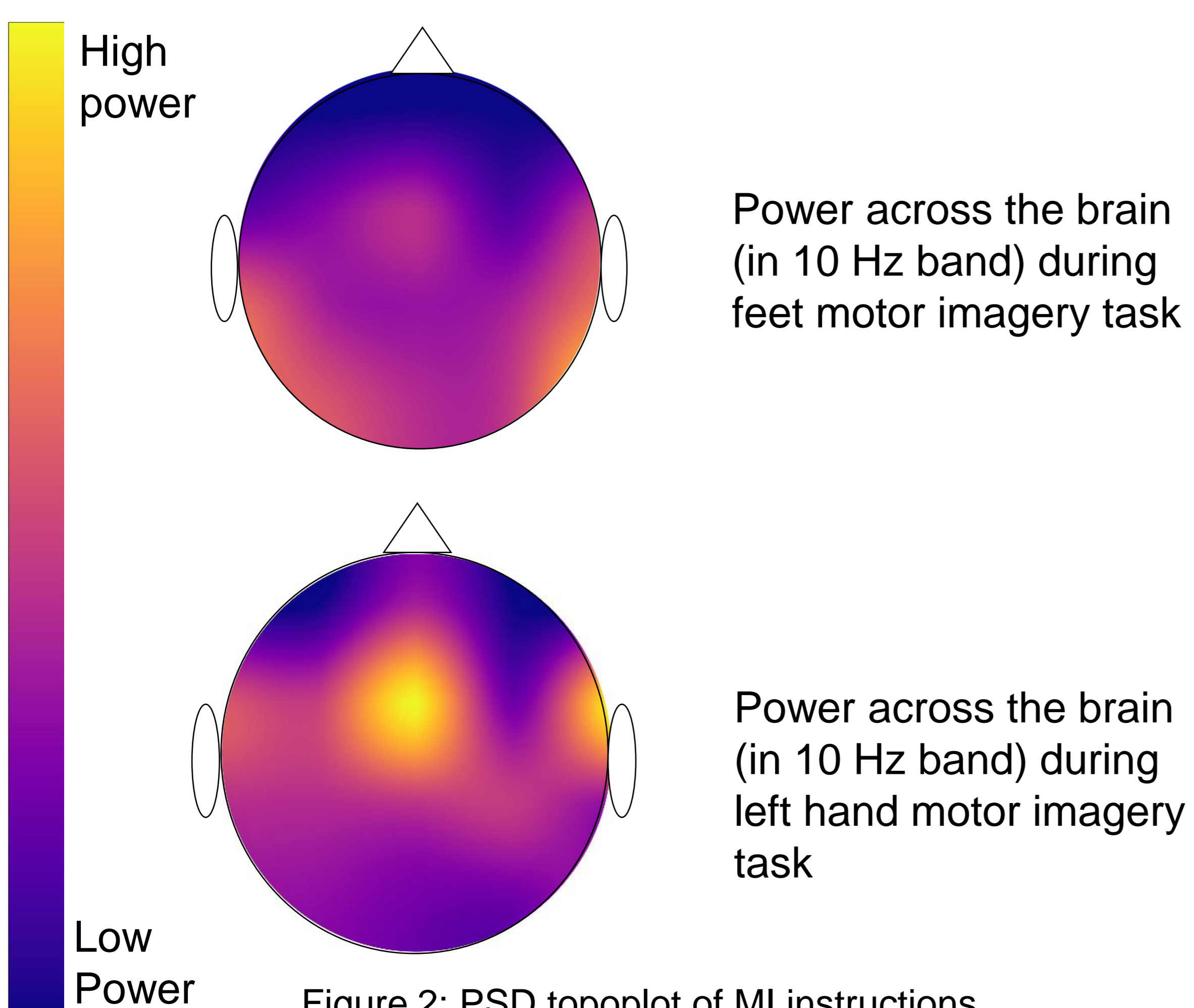


Figure 2: PSD topoplots of MI instructions

## References

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- Morbidi, F., Devigne, L., Teodorescu, C. S., Fraudet, B., Leblong, E., Carlson, T., . . . Ragot, N. (2022). Assistive Robotic Technologies for Next-Generation Smart Wheelchairs: Codesign and Modularity to Improve Users' Quality of Life
- Pacaux-Lemoine, M. - P., Habib, L., Sciacca, N., & Carlson, T. (2020). Emulated haptic shared control for brain-computer interfaces improves human-robot cooperation