

Should monetary policy care about redistribution?
Should fiscal policy care about inflation? Optimal
monetary policy with heterogeneous agents

François Le Grand^a, Alais Martin-Baillon^b, Xavier Ragot^b

^aEMLyon Business School and ETH Zurich ^b SciencesPo and OFCE

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Question

- The redistributive channels of monetary policy are now well-identified (Bilbiie, 2008; Algan, Challe Ragot, 2010; HANK, Kaplan, Moll, Violante 2018; Auclert 2018; Acharya and Dogra 2019...)
- How should optimal policy deal with redistributive effects?
What about fiscal policy?
- Hard to think about optimal monetary policy without considering fiscal policy, which deals with redistribution.

What we do

- We solve for optimal monetary and fiscal policy (**interest rate, capital tax, labor tax, public debt**) in an heterogeneous-agent model with aggregate shocks (public spending and TFP shocks) : (**HANK**) model
- We derive analytical results depending on available fiscal tools
- Provide a quantification (employment risk)

How we do it? Projection theory and Lagrangian Approach

This is a very difficult problem : How to solve for Ramsey problem in Heterogeneous-agent model? Methodological contribution :

- "Lagrangian Approach" (Marcet and Marimon 2019) to solve for Ramsey problem in Heterogeneous-agent models with aggregate shocks.
 - works very well in HANK (deals with occasionally binding credit constraint + Phillips curve is an Euler equation)
- Going to the data : : Truncation to obtain a finite-dimensional state-space (Le Grand and Ragot, 2019). Can be simulated with simple perturbation methods (Dynare), different from Reiter 2009; Preston, Roca 2007; Kim, Kolman, Kom 2010.

What we find

- Irrelevance result. With simple tools : linear capital and labor taxes, public debt monetary policy should not care about redistribution
- If either labor or capital taxes are missing, monetary policy must consider redistribution : price stability
- With imperfect fiscal policy : three new channels
 - Capital-tax channel
 - Real-wage channel
 - Public finance channel
- Quantitatively : Small deviation from price stability, except when labor and capital taxes are not optimally time-varying.

Selected literature Review

1. Redistributive effect Bilbiie 2008; Algan and Ragot, 2010; Kaplan, Moll Violante (2018), Auclert (2019), Acharya and Dogra (2019); Bayer, Luetticke, Pham-Dao, Tjaden (2019)
2. Fiscal, monetary interactions Chari, Kehoe (1999); Correia, Nicolini, Teles (2008) (consumption taxes).
3. Optimal monetary policy heterogeneous agents ;Nuno Thomas (2017); Bilbiie Ragot, (2017); Challe (2019); Acharya, Challe and Dogra (2020)
4. Bhandari, Evans, Golosov, and Sargent (2018) : lump-sum tax and income tax, primal approach : difficult to characterize the steady-state distribution. Acikgoz et al. (2019) optimal fiscal policy at the steady state.

Outline of the presentation

1. Environment
2. Optimal policy
3. Bringing the model to the data : The truncation theory
4. Numerical application

1 - Environment

- Unit mass of agents, discount factor β , (GHH)

$$U(c, l) = u \left(c - \frac{l^{1+1/\phi}}{1 + 1/\phi} \right).$$

- Y idiosyncratic states, $y_t \in \mathcal{E} \equiv \{1, \dots, Y\}$, productivity y_t .
- Markovian transition matrix for idiosyncratic risk T .

Households

The program (obvious notations)

$$\begin{aligned} \max_{\{c_t^i, l_t^i, a_t^i\}_{t=0}^{\infty}} \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u \left(c_t^i - \chi^{-1} \frac{l_{t+1}^{i, 1+1/\varphi}}{1 + 1/\varphi} \right) \\ c_t^i + a_t^i = R_t a_{t-1}^i + w_t y_t^i l_t^i \\ a_t^i \geq -\bar{a}, \quad c_t^i > 0, \quad l_t^i > 0. \end{aligned}$$

Households

The program (obvious notations)

$$\begin{aligned} \max_{\{c_t^i, l_t^i, a_t^i\}_{t=0}^{\infty}} \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u \left(c_t^i - \chi^{-1} \frac{l_{t+1}^{i, 1+1/\varphi}}{1 + 1/\varphi} \right) \\ c_t^i + a_t^i = R_t a_{t-1}^i + w_t y_t^i l_t^i \\ a_t^i \geq -\bar{a}, c_t^i > 0, l_t^i > 0. \end{aligned}$$

First-order conditions

$$\begin{aligned} U_c(c_t^i, l_t) &= \beta \mathbb{E}_t \left[(1 + r_{t+1}) U_c(c_{t+1}^i, l_{t+1}) \right] + \nu_t^i \\ l_t^{i, 1/\varphi} &= \chi w_t y_t^i \end{aligned}$$

Production

Standard assumption to get the Philipps curve

- Monopolistic competition, demand elasticity ε
- Rotemberg price adjustment cost

$$\frac{\kappa}{2} \left(\frac{p_t(j)}{p_{t-1}(j)} - 1 \right)^2 Y_t$$

- Steady-state subsidy (no steady-state distortion)
- Marginal utility of firm owner M_t

Production

Firm produce with capital and labor a differentiated product.

$$Z_t \tilde{k}_t(j)^\alpha \tilde{l}_t(j)^{1-\alpha}$$

Cost minimization gives the marginal cost is $\zeta_t(j)$

$$\zeta_t = \frac{1}{Z_t} \left(\frac{\tilde{r}_t}{\alpha} \right)^\alpha \left(\frac{\tilde{w}_t}{1-\alpha} \right)^{1-\alpha}$$

Production

Phillips curve

$$\begin{aligned}\Pi_t(\Pi_t - 1) &= \frac{\varepsilon - 1}{\kappa}(\zeta_t - 1) \\ &\quad + \beta \mathbb{E}_t \Pi_{t+1}(\Pi_{t+1} - 1) \frac{Y_{t+1}}{Y_t} \frac{M_{t+1}}{M_t}\end{aligned}$$

Pricing kernel : Formally, the expression of M_t is:

$$M_t = \beta^t \int_i a_{t-1}^i U_c(c_t^i, l_t^i) \ell(di)$$

Monoploy profits Ω_t taxed by the government

$$\Omega_t = \left(1 - \zeta_t - \frac{\kappa}{2} \pi_t^2\right) Y_t.$$

Government

- One-period debt B_t , all assets have the same return r_t in period t .
- (Exogenous) Public spending G_t financed by taxes on capital τ_t^K and labor τ_t^L .

$$w_t = (1 - \tau_t^L)\tilde{w}_t, 1 + r_t = R_t = (1 - \tau_t^K)\frac{1 + i_{t-1}}{\Pi_t}$$

- Budget constraint (post tax, as in Chamley)

$$G_t + B_{t-1} + r_t(B_{t-1} + K_{t-1}) + w_t L_t = \\ B_t + \left(1 - \frac{\kappa}{2}\pi_t^2\right) Y_t.$$

Market equilibria

$$\int_i a_t^i \ell(di) = B_t + K_t$$

$$\int_i c_t^i \ell(di) + K_t = Y_t + (1 - \delta)K_{t-1}$$

$$\int_i y_t^i l_t^i \ell(di) = L_t$$

Question

How should the government choose **time-varying monetary and fiscal policy** $i_{t-1}, \tau_t^K, \tau_t^L, B_t$, after shocks on G_t or z_t ?

2 - Optimal policy

2 - Optimal policy

$$\max_{(R_t, w_t, i_t, \bar{R}_t, \tilde{w}_t, \tau_t^K, \tau_t^L, B_t, \Pi_t, (a_t^i, c_t^i, l_t^i)_i)_{t \geq 0}} \mathbb{E}_0 \left[\sum_{t=0}^{\infty} \beta^t \int_i \omega_t^i U(c_t^i, l_t^i) \ell(di) \right],$$

$$G_t + B_{t-1} + r_t (B_{t-1} + K_{t-1}) + w_t L_t = B_t + \left(1 - \frac{\kappa}{2} \pi_t^2\right) Y_t.$$

$$a_t^i + c_t^i = y_i l_t^i w_t + (1 + r_t) a_{t-1}^i$$

$$U_c(c_t^i, l_t^i) = \beta \mathbb{E}_t [U_c(c_{t+1}^i, l_{t+1}^i) (1 + r_{t+1})] + \nu_t^i,$$

$$l_t^{i,1/\varphi} = \chi w_t y_t^i,$$

$$\nu_t^i (a_t^i + \bar{a}) = 0$$

$$\begin{aligned} \Pi_t (\Pi_t - 1) &= \frac{\varepsilon - 1}{\kappa} \left(\zeta (\tilde{R}_t, \tilde{w}_t) - 1 \right) \\ &\quad + \beta \mathbb{E}_t \Pi_{t+1} (\Pi_{t+1} - 1) \frac{Y_{t+1}}{Y_t} \frac{M_{t+1}}{M_t} \end{aligned}$$

$$K_t + B_t = \int_i a_t^i \ell(di), L_t = \int_i y_t^i l_t^i \ell(di),$$

Reformulation

Key idea : Using [Marcet and Marimon \(2019\)](#) methodology :

- Factorization of the Lagrangian to get rid of expectations.
- α_t Lagrange multiplier on the Phillips cuve
- μ_t Lagrange multiplier on the budget of the State
- λ_t^i Lagrange multiplier on the Euler equation in period t
- KEY : $\lambda_t^i \times \nu_t^i = 0$ (Euler equation or not!)

Reformulation

$$\begin{aligned}
 J = & \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t \\
 & \int_i \omega_t^i U(c_t^i, l_t^i) \ell(di) - \beta^t \int_i (\omega_t^i \lambda_t^i - (1 + r_t) \lambda_{t-1}^i \omega_{t-1}^i) U_c(c_t^i, l_t^i) \ell(di) \\
 & - (\alpha_t - \alpha_{t-1}) (\Pi_t (\Pi_t - 1) Y_t M_t) + \frac{\varepsilon - 1}{\kappa} \alpha_t (\zeta_t - 1) Y_t M_t \\
 & - \mu_t \left(G_t + B_{t-1} + r_t (B_{t-1} + K_{t-1}) + w_t L_t - B_t - \left(1 - \frac{\kappa}{2} \pi_t^2 \right) Y_t \right)
 \end{aligned}$$

subject to

$$\begin{aligned}
 a_t^i + c_t^i &= \theta_i l_t^i w_t + (1 + r_t) a_{t-1}^i \\
 l_t^{i,1/\varphi} &= \chi w_t y_t^i, \\
 K_t + B_t &= \int_i a_t^i \ell(di), L_t = \int_i y_t^i l_t^i \ell(di),
 \end{aligned}$$

Analytical Results : 1

Define the real-economy as the economy without monetary friction ($\kappa = 0$)

Proposition

When both labor and capital taxes are available, $\Pi_t = 1$.

The government reproduces the (time-varying) real-economy allocation after shocks on G_t or z_t

The real economy is the constrained-efficient economy : Useful benchmark

Intuition

- $\Pi_t = 1$ can be obtained by several combinations of instruments.

Simple policy :

$$r_t = (1 - \tau_t^K) i_{t-1}.$$

- and the policy rule ($\phi^\Pi > 1$ for determinacy)

$$i_{t-1} = \mathbb{E}_t R_{t+1} + \phi^\Pi (\Pi_t - 1),$$

- $\mathbb{E}_t \tau_{t+1}^K = 0$: The capital tax in the period only adjusts to the new information
- Not enough : The labor tax τ_{t+1}^K is time-varying to adjust to obtain the right labor share. set.

Analytical Results

In the paper, analytical characterization of :

- Optimal labor tax and monetary policy , with constant capital tax
- Optimal capital tax and monetary policy, with constant labor tax
- Optimal monetary policy, with exogenous fiscal system

Involved algebra, simulation instead

3 - Bringing the model to the data : The truncation theory

- For agents, the state space is the joint distribution $\Lambda(\lambda, a)$ over Lagrange multiplier and wealth
- No algorithm to find the steady state (see [Acikgoz et al. 2019](#) for an attempt)
- Main Idea : construct a consistent finite dimensional model, that can be simulated.
- We go back in the sequential representation (history representation) to provide a theory based on truncation.
- Instead of keeping track of the whole history of each agent, assume an insurance system implies that only the last N periods are relevant : [Finite number of different agents](#)

Consistent Truncated model

- Consider an integer $N \geq 1$.
- Agents have history $y^{i,t} = \{y_1, \dots, y_t\}$ at period $t \geq 1$.
- Number of histories for the last N periods
$$y^k = \{y_{-N}, \dots, y_0\}, k = 1 \dots Y^N$$
- Knowing your history at period t , y^k , can easily deduce the probability $\Pi_{k,k'}$ of $y^{k'}$ next period.
- Easy to compute the measure of agents having each history S_{y^k}

Approximated model : Assumptions

- Agents face a fiscal system, which depends on the history over the last $N + 1$ periods.
- Agents face preference shocks which depend on their current N -period history: ξ_{y^k} (Important, see below)

Recursive representation ($k = 1 \dots Y^{N+1}$)

$$V(a, y^{k, N+1}, X) = \max_{c, a', l} \xi_{y^k, N} U(c, l) + \beta \mathbb{E} V(a', y^{k', N+1}, X')$$

subject to

$$\begin{aligned} c + a' &= Ra + wy_i l + T(y^{k, N+1}) \\ a' &\geq 0 \end{aligned}$$

Proposition

There exists a balanced fiscal system such that all agents with the same history $y^{k,N}$ have the same beginning of period wealth.

The economy is, for each $k = 1 \dots Y^N$

$$\xi_k U'(c_k, l_k) = \beta \mathbb{E} R' \xi_{k'} U'(c_{k'}, l_{k'}) + \nu_k$$

$$c_k + a'_k = R \tilde{a}_k + w y_k l_k$$

$$l_k = (\chi y_k w)^\phi$$

with

$$\tilde{a}_k = \sum_{l=1 \dots Y^N} \frac{S_{l,-1}}{S_k} \Pi_{l,k} a'_{l,-1}.$$

Total savings $A = \sum_{k=1}^{Y^N} S_k a'_k$.

Consistent model : What is ξ ?

Consider the (true) Bewley model without aggregate shock.

Denote as $\Lambda(a, y^k)$, $k = 1 \dots Y^N$, the distribution of wealth of agents having history y^k .

Average consumption

$$\hat{a}'_k = \int a' (a, y^k) \Lambda(a, y^k)$$

$$\hat{c}_k = \int c(a, y^k) \Lambda(a, y^k)$$

$$\hat{l}_k = \int l(a, y^k) \Lambda(a, y^k)$$

Proposition

For any $N \geq 1$, there are preferences parameters ξ_k , $k = 1 \dots Y^N$, such that the allocations are the same in the truncated in “true” Bewley model :

$$\hat{a}'_k = a_k$$

$$\hat{c}_k = c_k$$

$$\hat{l}_k = l_k$$

In addition, when $N \rightarrow \infty$, $\xi_k \rightarrow 1$.

Intuition

Average marginal utility by history in the "true" Bewley model:

$$u'_k = \int U'_c \left(c \left(a, y^k \right), l_k \left(a, y^k \right) \right) \Lambda \left(a, y^k \right)$$

Then

$$\xi_k \simeq \frac{u'_k}{U'_c(c_k, l_k)}$$

We solve

$$\max_{\left(R_t, w_t, i_t, \tilde{R}_t, \tilde{w}_t, \tau_t^K, \tau_t^L, B_t, \Pi_t, (a'_{k,t}, c_{k,t}, l_{k,t})_{k=1 \dots Y^N}\right)_{t \geq 0}} \mathbb{E}_0 \left[\sum_{t=0}^{\infty} \beta^t \sum_{k=1}^{Y^N} S_{k,t} \xi_k U(c_{k,t}, l_{k,t}) \right]$$

$$\xi_k U'(c_{k,t}, l_{k,t}) = \beta \mathbb{E} R_{t+1} \xi_{k'} U'(c_{k',t+1}, l_{k',t+1}) + \nu_{k,t}$$

$$c_{k,t} + a_{k,t} = R_t \tilde{a}_{k,t} + w_t y_k l_{k,t}$$

$$l_{k,t} = (\chi y_{k,t} w_t)^\phi$$

$$\tilde{a}_{k,t} = \sum_{l=1 \dots Y^N} \frac{S_{l,t-1}}{S_{k,t}} \Pi_{l,k,t} a_{l,t-1}$$

$$A_t = \sum_{k=1}^{Y^N} S_{k,t} a_{k,t}$$

+ production side and government budget constraint.

Algorithm to find the steady state and simulation

1. Choose N
2. Choose instruments (i, τ^K, τ^L, B)
3. Solve for the true Bewley model, compute ξ_k
4. Find the equilibrium values of Lagrange multipliers on the Truncated model λ_k (easy).
5. Check the first-order conditions of the planner on the Truncated model
6. Iterate on the instruments (i, τ^K, τ^L, B)
7. Check that doesn't depend on N
8. Use perturbation methods to solve the model with aggregate shocks (DYNARE)

4 - Numerical application

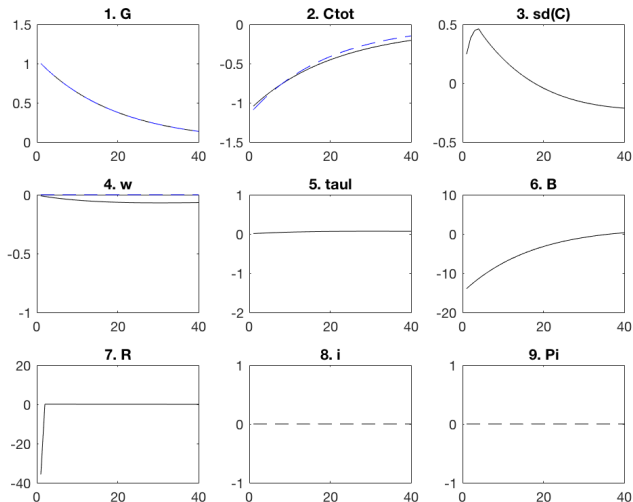
Preliminary - Economy without capital, employment risk

	Values	Description
β	0.99	Discount factor
σ	1	Log utility
ϕ	0.5	Chetty et al. (2011)
δ/wl	50%	Replacement rate
κ	100	Rotemberg coeff.
ϵ	6	Elasticity of sub.
f	80%	Job finding rate
s	5%	Job separation rate
G	0	Steady-state gov. spend.
ρ_g	97%	Persistence shock
σ_g	7%	St. dev
N	4	Thus $2 * 2^4 = 32$ agents

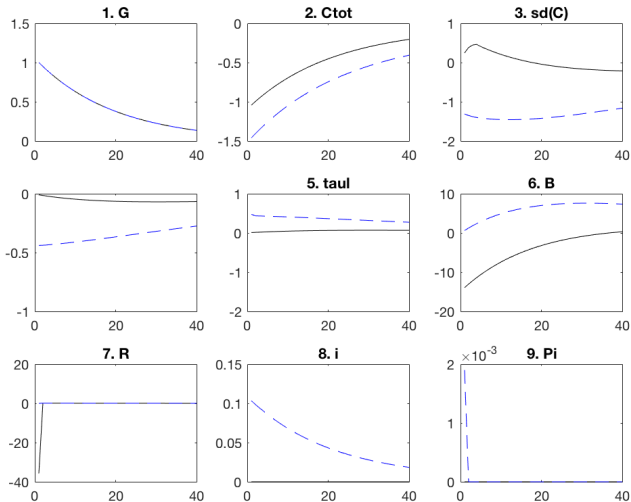
Steady-state results

- Optimal inflation rate 0%, as expected
- Public debt 42% of quarterly GDP, consistent with (Le Grand and Ragot 2017) in an economy with capital
- Capital tax 0.001% very small
- Labor tax 4% to pay interest on public debt.

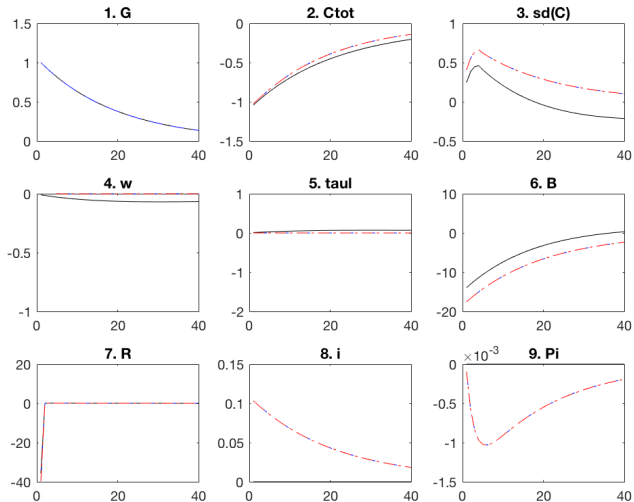
Comparison between first-best and constrained-efficient economy (CE)



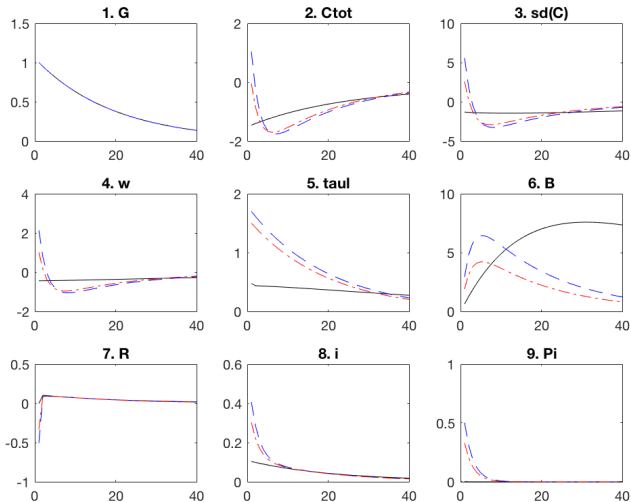
Comparison CE and labor tax only



Comparison CE and capital tax only



Comparison monetary policy only, no optimal fiscal policy



Conclusion

- We derive optimal monetary policy with heterogeneous agents, with rich set of fiscal tools.
- **Projection theory** and **Lagrange approach** : very efficient tool for monetary policy with heterogeneous agents
- Strong deviation from price stability with exogenous fiscal dynamics (fiscal dominance)
- **Next** : More quantitative...

Reformulation

The Ramsey program on the projected model

$$\max_{((a_{h,t}, c_{h,t}, l_{h,t})_{h \in \mathcal{H}}, \phi_t, \tau_t)_{t \geq 0}} \mathbb{E}_0 \left[\sum_{t=0}^{\infty} \beta^t \sum_{h \in \mathcal{H}} S_{h,t} \xi_{h,t}^U U(c_{h,t}, l_{h,t}) \right],$$

with

$$\forall h \in \mathcal{H} \setminus \mathcal{C}, \quad \xi_{h,t}^u U_c(c_{h,t}, l_{h,t}) - \beta \mathbb{E}(1 + r_{t+1}) \sum_{\tilde{h} \in \mathcal{H}} \Pi_{h\tilde{h}, t+1}^u \xi_{\tilde{h}, t+1}^u U_c(c_{\tilde{h}, t+1}, l_{\tilde{h}, t+1}) = 0,$$

$$\forall h \in \mathcal{C}, \quad a_{h,t} = -\bar{a},$$

$$\forall h \in \mathcal{H}, \quad l_{h,t} = \chi^\varphi w_t^\varphi y_h^\varphi,$$

$$\forall h \in \mathcal{H}, \quad c_{h,t} + a_{h,t} \leq (1 + r_t) \sum_{\tilde{h} \in \mathcal{H}} \Pi_{h\tilde{h}, t}^a \frac{S_{\tilde{h}, t}}{S_{h, t}} a_{\tilde{h}, t-1} + l_{h,t} y_h w_t,$$

Reformulation with the projected model [\(Go back\)](#)

Ramsey problem can be simplified into:

$$\begin{aligned} \max_{((a_{h,t}, c_{h,t}, l_{h,t})_{h \in \mathcal{H}})_{t \geq 0}} \quad & \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t \sum_{h \in \mathcal{H}} S_{h,t} \left(\xi_{h,t}^U U(c_{h,t}, l_{h,t}) \right. \\ & \left. - (\lambda_{h,t} - (1 + r_t) \Lambda_{h,t}) \xi_{h,t}^u U_c(c_{h,t}, l_{h,t}) \right) \end{aligned} \quad (1)$$

$$\text{s.t. } \lambda_{h,t} = 0 \text{ if } a_{h,t} = -\bar{a}, \quad (2)$$

with

$$\Lambda_{h,t} \equiv \frac{\sum_{\tilde{h} \in \mathcal{H}} S_{\tilde{h},t} \Pi_{\tilde{h}h,t}^S \lambda_{\tilde{h},t-1}}{S_{h,t}} \quad (3)$$