

## Predicting extubation failure using complexity measures

### Motivation

- Extubating a patient on ventilator support too early or too late can lead to fatal outcomes
- Major post extubation complications reported between 25 and 50% cases(1; 2).
- Growing evidence that measures from complex dynamical systems can help predict extubation failure(2).

### Question

- Are there any differences in complexity based measures between children who failed extubation and those who do not?
- Can these differences be used to predict extubation failure?

### Method

- We start with heart rate and respiratory rate data from 6 hours before the extubation
- The standard deviation, Higuchi dimension and multiscale entropy of the data are calculated
- Heart and respiratory rate measures are known to be closely related to age(3).
- Differences are checked using a t-test and studied separately for younger and older children.

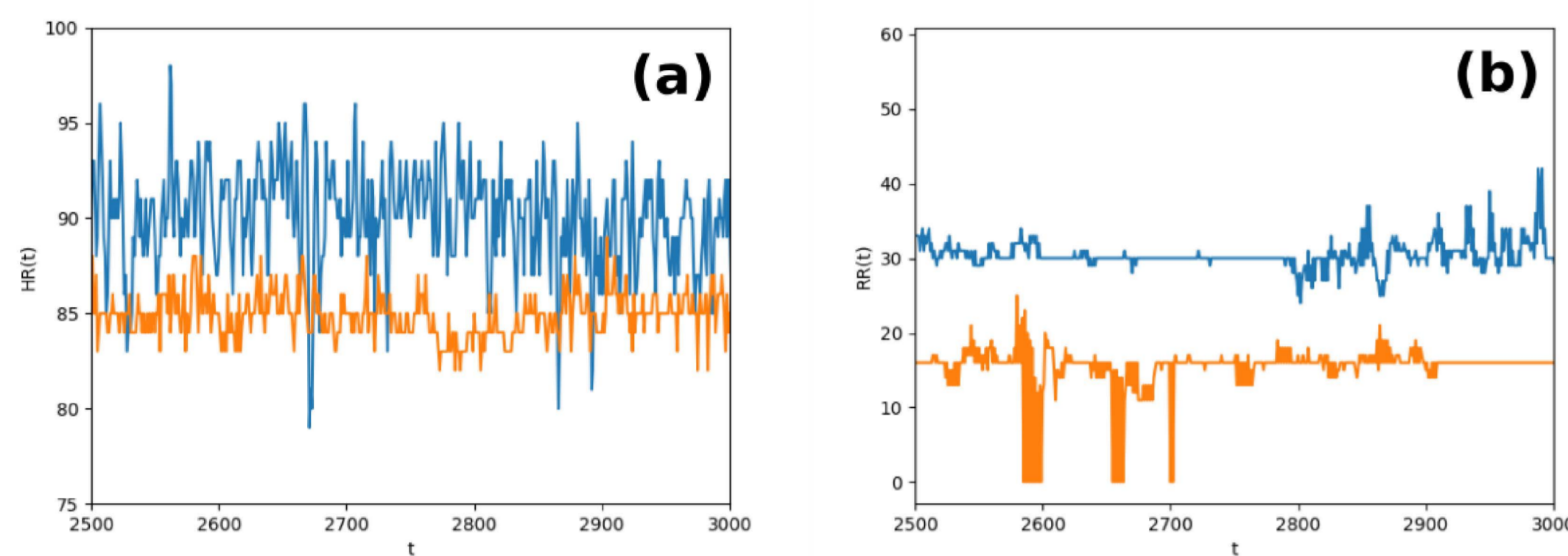


Figure 1: Sample time series of (a) heart rate and (b) respiratory rate from a patient who did not fail extubation (blue) and one who did (orange)

### Heart rate

- No significant differences were found in the three quantifiers between the children who failed extubation and those who did not.
- Sample was then divided into categories according to median age.
- No significant differences were found even after, in either group.

### Respiratory rate

- No significant differences was found between children who failed extubation and those who did not
- Sample was then divided into categories according to median age.
- No significant differences were found in younger children who failed extubation and did not.
- Significant differences were found between the two groups for standard deviation and multiscale entropy for older children.

Property	$\mu_F \pm SD$	$\mu_S \pm SD$	t-statistic	p-value
$SD_Y$	$9.609 \pm 3.724$	$8.525 \pm 4.170$	1.574	0.124
$MSE_Y$	$1.125 \pm 0.355$	$1.129 \pm 0.337$	0.057	0.955
$HD_Y$	$1.850 \pm 0.142$	$1.866 \pm 0.116$	-0.612	0.545
$SD_O$	$4.888 \pm 2.607$	$4.093 \pm 2.163$	2.212	0.030*
$MSE_O$	$0.964 \pm 0.390$	$0.835 \pm 0.463$	2.331	0.027*
$HD_O$	$1.836 \pm 0.150$	$1.846 \pm 0.149$	-0.501	0.617

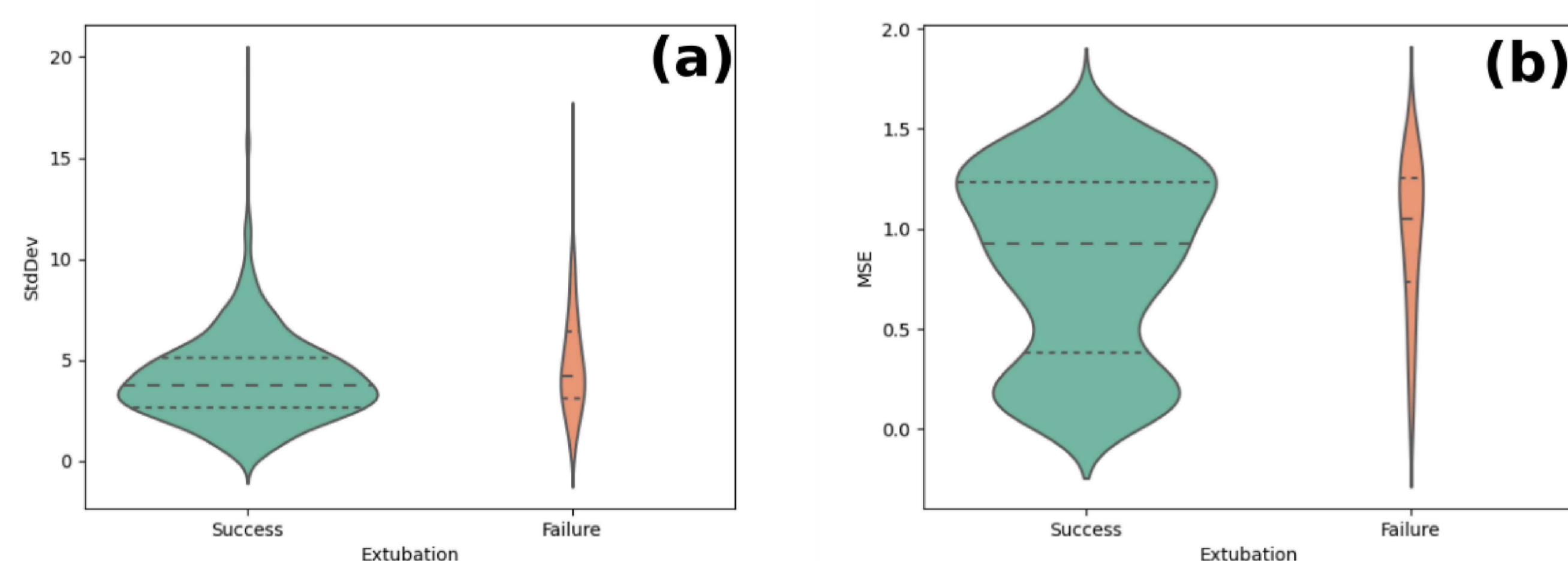


Figure 2: Differences in the distributions of (a) standard deviation and (b) multi-scale entropy between children who failed extubation (orange) and those who did not (green), in a sample of older children.

### Conclusions and future directions

- Shows promise in the use of nonlinear time series measures to predict extubation failure, in limited cases.
- Need to replicate with a larger sample.
- Possible to use in combination with machine learning tools in order to achieve greater accuracy.

### Acknowledgements

This work uses data collected from the GOSH ICU, and was processed as part of the GOSH Turing data science group held in January 2020.

### References

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## Predicting dynamical properties using echo state networks

### Motivation

- Recurrent neural networks, such as echo state networks(ESN), have shown promise in predicting chaotic attractors upto 6 or 7 Lyapunov times (4; 5).
- But the algorithm can learn the attractor, or the “climate” of the system with comparative ease(6).

### Question

- How well do echo state networks predict the attractor climate?
- How does the prediction accuracy change with data length and size of the hidden layer (reservoir size)?

### Echo State Networks

- The echo state network consists of an input layer, a hidden reservoir layer and an output layer(4).
- The reservoir weights are chosen randomly and fixed throughout the training.
- $n$ : time step,  $u(n)$ : input state,  $x(n)$ : reservoir state,  $y(n)$ : output state,  $W$ : reservoir strength matrix,  $W^{in}$ : input weight matrix,  $W^{out}$ : output feedback matrix and  $f$ : sigmoid function, the state update equation of the reservoir is given as

$$\vec{x}(n+1) = f(W\vec{x}(n) + W^{in}\vec{u}(n+1) + W^{out}\vec{y}(n))$$

- The extended system,  $\vec{z}$  is the concatenation of the reservoir and input states,  $\vec{z}(n) = [\vec{x}(n); \vec{u}(n)]$ , whose state is given by

$$\vec{y}(n) = f(W^{out}\vec{z}(n))$$

- Only the  $W^{out}$  is trained during the training phase, greatly reducing the computation time.

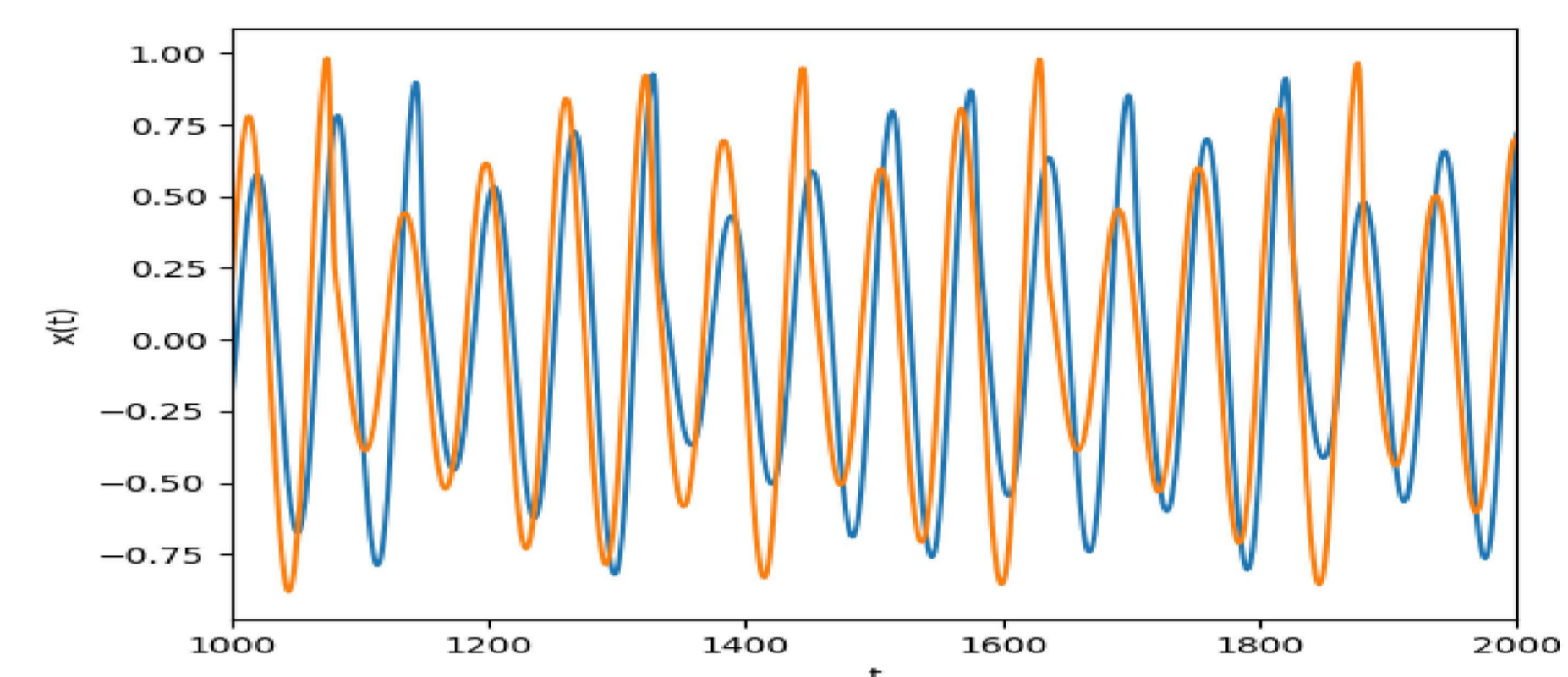


Figure 3: Comparison of the original time series from the Rössler (blue) and the prediction of the ESN(orange) using 500 data points and a reservoir size of 1000.

### Method

- Start with time series from a dynamical system (we use the Rössler system)
- Calculate an attractor metric (in our case, the correlation dimension).
- Train ESN of reservoir size  $N$  with a time series of length  $L$ .
- Predict the future evolution using the ESN and calculate its correlation dimension.
- Vary  $N$  and  $L$  and repeat process

### Results

- The fractal dimension did not show significant variation with  $N$  or  $L$ .
- The stability of the echo state network was poor, and the network was often found to be unstable.

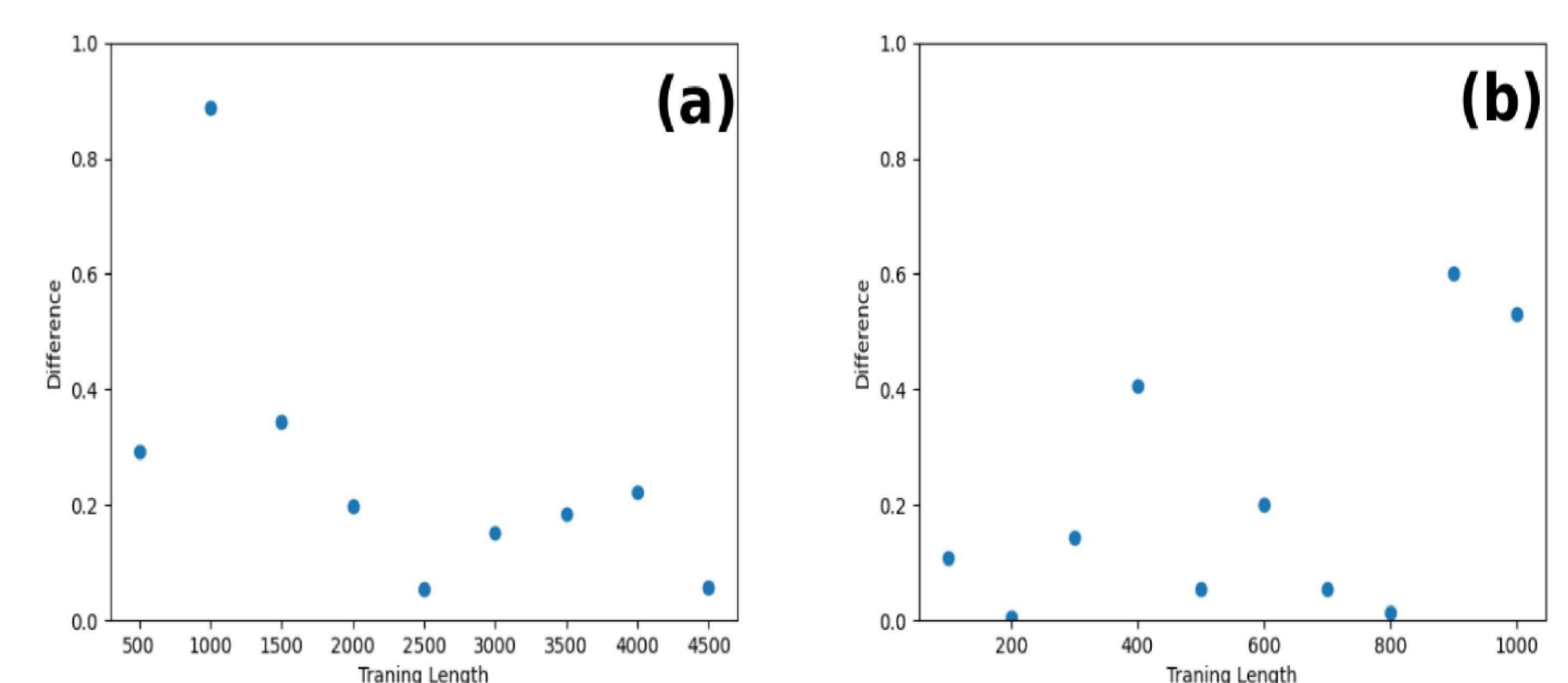


Figure 4: Variation of the correlation dimension from the original value varying (a) length of training data (b) size of the hidden layer (reservoir)

### Conclusions and future directions

- Attractor properties of a short chaotic time-series can be calculated from ESN based predictions
- This could be in part because the original dynamics was noise free and low dimensional
- One could use these to interpolate through gaps, when conducting nonlinear analysis
- Useful when classifying short waveform time series in the ICU, using complexity based analysis.
- Need to improve ESN stability by fine tuning hyper parameters