

# Adaptive Tensor Testing

Peter Hoff  
Duke University

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# Outline

Tensor data and models

FAB tests and CIs

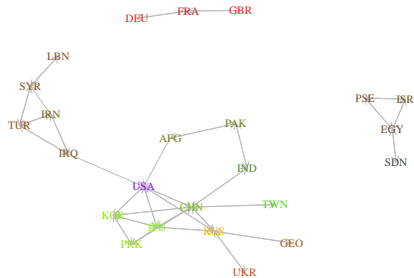
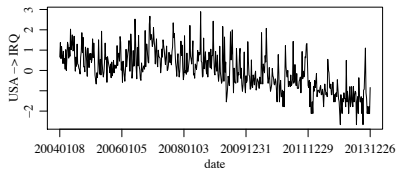
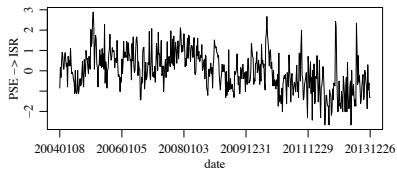
AFAB tests and CIs

Multilevel data

Linear regression

Tensor parameters

## ICEWS data



Data: [www.lockheedmartin.com/us/products/W-ICEWS/iData.html](http://www.lockheedmartin.com/us/products/W-ICEWS/iData.html)

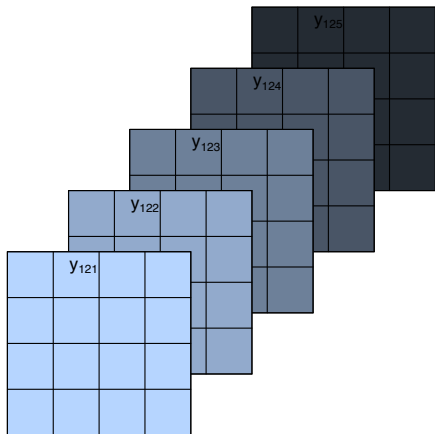
(Thanks to Mike Ward, Duke University, for data access and polysci consulting.)

## Dynamic network data

A time series of sociomatrices:

$$\mathbf{Y} = \{\mathbf{Y}_t : t = 1, \dots, T\}$$

$y_{i,j,t}$  = time- $t$  relation from  $i$  to  $j$ .

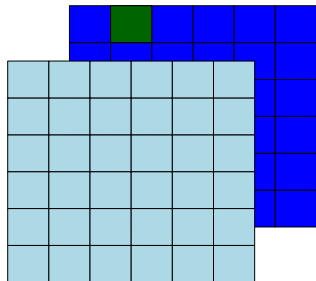


## Temporal dependence

How does  $y_{i,j,t}$  depend on  $\mathbf{Y}_{t-1}$ ?

Maybe

- $y_{i,j,t-1}$ ?
- $y_{j,i,t-1}$ ?
- $y_{i,k,t-1}, y_{k,j,t-1}$ ?
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- $y_{k,l,t-1}$ ?

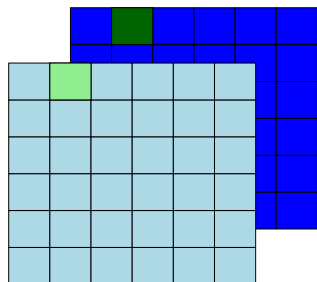


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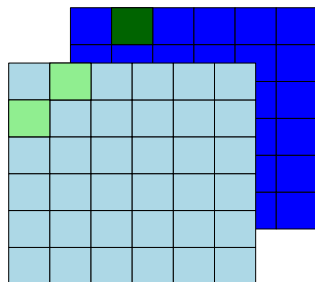


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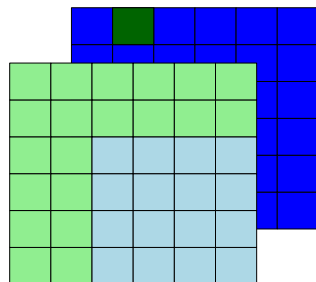


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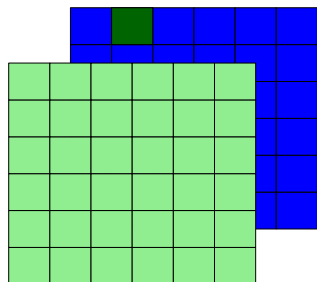


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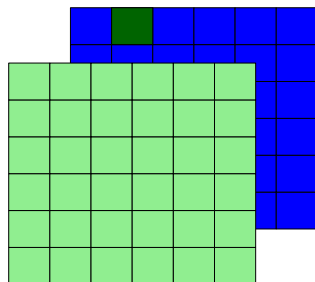


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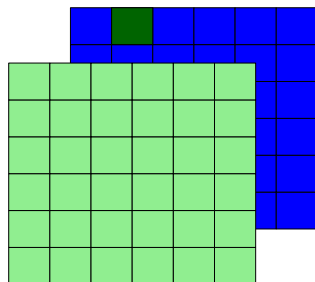


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## First order VAR model

Let

- $\mathbf{y}_t = \text{vec}(\mathbf{Y}_t)$
- $\mathbf{x}_t = \text{vec}(\mathbf{X}_t)$

**VAR:** A first-order VAR model posits that

$$\mathbf{y}_t = \Theta \mathbf{x}_t + \mathbf{e}_t, \quad E[\mathbf{e}_t] = \mathbf{0}, \quad E[\mathbf{e}_t \mathbf{e}_s^T] = \begin{cases} \Sigma & \text{if } t = s \\ \mathbf{0} & \text{if } t \neq s, \end{cases}$$

where  $\Theta$  and  $\Sigma$  are parameters to be estimated.

Is it possible to estimate an effect of each entry of  $\mathbf{x}_t$  on each entry of  $\mathbf{y}_t$ ?

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## Multilinear models

Assume  $\Theta$  is low-dimensional:

$$\mathbf{Y}_t = \mathbf{A}\mathbf{X}_t\mathbf{B}^\top + \mathbf{E}_t$$

$$\mathbf{y}_t = (\mathbf{B} \otimes \mathbf{A})\mathbf{x}_t + \mathbf{e}_t$$

Extension to higher-dimensional tensors:

$$\mathbf{Y}_t = \mathbf{X}_t \times \{\mathbf{A}, \mathbf{B}, \mathbf{C}\} + \mathbf{E}_t$$

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(Hoff 2015)

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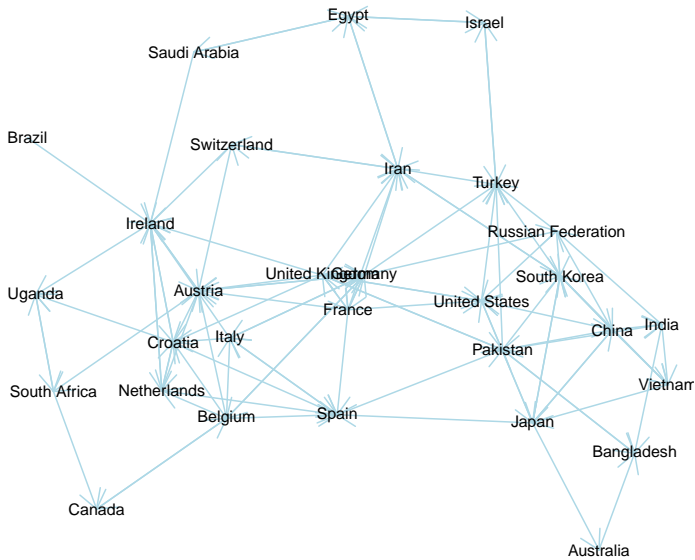
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(Hoff 2015)



## Social influence model for symmetric relations

$$\mathbf{y}_t = (\mathbf{A} \otimes \mathbf{A})\mathbf{x}_t + \mathbf{e}_t$$



## Inference concerns

**Restricted model:**  $\mathbf{y}_t = (\mathbf{A} \otimes \mathbf{A})\mathbf{x}_t + \mathbf{e}_t$

- parameter estimates stable;
- model is wrong;
- CIs wont have proper coverage, hard to interpret.

**Full model:**  $\mathbf{y}_t = \Theta\mathbf{x}_t + \mathbf{e}_t$

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**Objective:** Obtain proper CIs that adapt to restricted model.

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- improve precision if model is correct.

**Strategy:** Use tests with more power in likely parts of parameter space, less power elsewhere.

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## Bayes-optimal confidence interval

### Normal model:

- $y \sim N(\theta, \sigma^2)$ ,  $\sigma^2$  known.
- $\pi(\theta)$  is prior information about  $\theta$ .

**Goal:** Construct confidence interval  $C$  having

- Constant coverage:  $\Pr(\theta \in C(y)|\theta) = 1 - \alpha \forall \theta$ .
- Optimal precision:  $\int \int |C(y)| p(dy|\theta) \pi(d\theta) < \int \int |\tilde{C}(y)| p(dy|\theta) \pi(d\theta)$ .

The first criterion is “frequentist” - conditional on  $\theta_j$ .

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**F.A.B.** : Frequentist, Assisted by Bayes.

## All CIs

### UMAU procedure:

$$C_{1/2}(y) = \{\theta : y + \sigma z_{\alpha/2} < \theta < y + \sigma z_{1-\alpha/2}\}$$

### Any procedure:

$$C_s(y) = \{\theta : y + \sigma z_{\alpha(1-s)} < \theta < y + \sigma z_{1-\alpha s}\}$$

In fact,  $s$  may depend on  $\theta$ : If  $s : \mathbb{R} \rightarrow [0, 1]$  then

$A_s(\theta) = \{y : y + \sigma z_{\alpha(1-s(\theta))} < \theta < y + \sigma z_{1-\alpha s(\theta)}\}$  is a class of level- $\alpha$  tests;

$C_s(y) = \{\theta : y + \sigma z_{\alpha(1-s(\theta))} < \theta < y + \sigma z_{1-\alpha s(\theta)}\}$  is a  $1 - \alpha$  CR.

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## Properties of $C_s$

1.  $\Pr(\theta \in C_s(y)|\theta) = 1 - \alpha$ .
2.  $C_s(y)$  is an interval if  $s(\theta)$  is monotonic (not necessary).
3. In the monotonic case, the interval can be found by solving

$$\theta^L = y + \sigma z_{\alpha(1-s(\theta^L))}$$

$$\theta^U = y + \sigma z_{1-\alpha s(\theta^U)}$$

noting that  $\theta^L < y + \sigma z_\alpha$  and  $y + \sigma z_{1-\alpha} < \theta^U$ .

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## Optimal $s$ -function

If  $\pi(\theta)$  is the  $N(\mu, \tau^2)$  density, then

$$R(\pi, C_s) = \int \int |C_s(y)| p(dy|\theta) \pi(d\theta)$$

is minimized by

$$s(\theta) = g^{-1}(2\sigma(\theta - \mu)/\tau^2)$$

$$g(s) = \Phi^{-1}(\alpha s) - \Phi^{-1}(\alpha(1 - s))$$

This  $s$ -function yields Pratt's (1963)  $z$ -interval.

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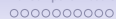
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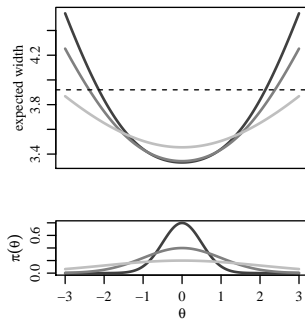
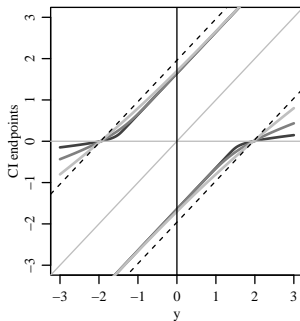
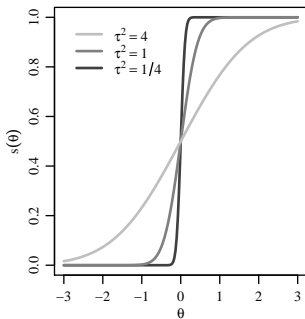
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## Bayes-optimal frequentist procedure





## Limitations of FAB z-interval

This idea has not been widely adopted:

- Pratt's original derivation hard to generalize for unknown variance.
- Non-Bayesians uneasy with specifying a prior distribution.
- Bayesians less concerned with frequentist coverage.

We address some of these issues:

- Extend z-interval to  $t$ -interval using  $s$ -functions.
- Apply method in multiparameter problems, sharing information.
  - "prior" is determined by data;
  - exact frequentist coverage is maintained.

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- Pratt's original derivation hard to generalize for unknown variance.
- Non-Bayesians uneasy with specifying a prior distribution.
- Bayesians less concerned with frequentist coverage.

We address some of these issues:

- Extend  $z$ -interval to  $t$ -interval using  $s$ -functions.
- Apply method in multiparameter problems, sharing information.
  - "prior" is determined by data;
  - exact frequentist coverage is maintained.

Tensor data and models

FAB tests and CIs

**AFAB tests and CIs**

Multilevel data

Linear regression

Tensor parameters

## FAB $t$ -intervals

### Data:

$$\hat{\theta} \sim N(\theta, h^2 \sigma^2), \quad q \hat{\sigma}^2 / \sigma^2 \sim \chi_q^2$$

$h^2$  known,  $\hat{\theta}$  and  $\hat{\sigma}^2$  independent.

### UMAU CI:

$$C_{1/2}(\hat{\theta}, \hat{\sigma}) = \{\theta : \hat{\theta} + h \hat{\sigma} t_{\alpha/2} < \theta < \hat{\theta} + h \hat{\sigma} t_{1-\alpha/2}\}$$

### All CIs:

$$C_s(\hat{\theta}, \hat{\sigma}) = \{\theta : \hat{\theta} + h \hat{\sigma} t_{\alpha(1-s(\theta))} < \theta < \hat{\theta} + h \hat{\sigma} t_{1-\alpha s(\theta)}\}$$

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1.  $\Pr(\theta \in C_s(\hat{\theta}, \hat{\sigma}) | \theta, \sigma) = 1 - \alpha \forall (\theta, \sigma) \in \mathbb{R} \times \mathbb{R}^+$ ;
2. If  $s(\theta)$  nondecreasing,  $C_s(\hat{\theta}, \hat{\sigma})$  is an interval with probability 1;
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## Optimal and suboptimal spending functions

### Prior information:

$$\pi(\theta, \sigma^2), \quad E[(\theta, \sigma^2)] = (\mu, \sigma_0^2), \quad V[\theta] = \tau^2.$$

### Principled procedure:

Find Bayes optimal  $s$ -function under this prior (numerically).

### Simpler procedure:

Use Bayes optimal  $s$ -function from  $z$ -interval, with  $\theta \sim N(\mu, \tau^2)$ ,  $\sigma^2 = \sigma_0^2$ .

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Lacking a prior, can we obtain  $s(\theta)$  from data?

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- $\hat{\theta}$ ,  $\hat{\sigma}^2$  and  $\tilde{s}$  are independent, then

$$\Pr(\theta \in C_{\tilde{s}}(\hat{\theta}, \hat{\sigma}) | \theta, \sigma) = 1 - \alpha.$$

**AFAB procedure:**

- $\tilde{s}(\theta) = g^{-1}(2\tilde{\sigma}(\theta - \tilde{\mu})/\tilde{\tau}^2)$  ;
- $\tilde{\gamma} = (\tilde{\theta}, \tilde{\tau}^2, \tilde{\sigma}^2)$  estimated from data;
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Tensor data and models

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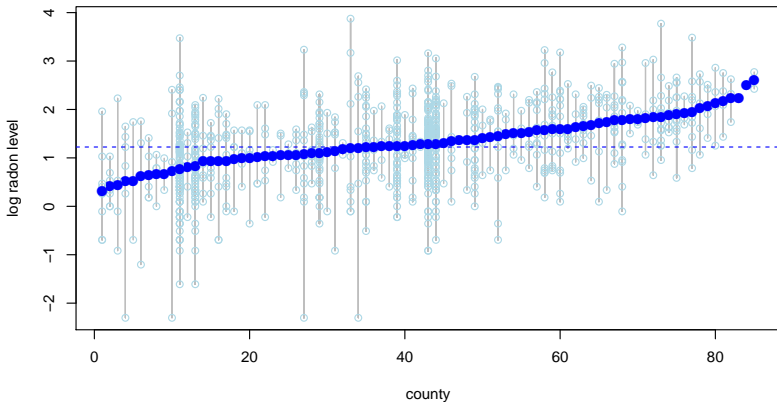
**Multilevel data**

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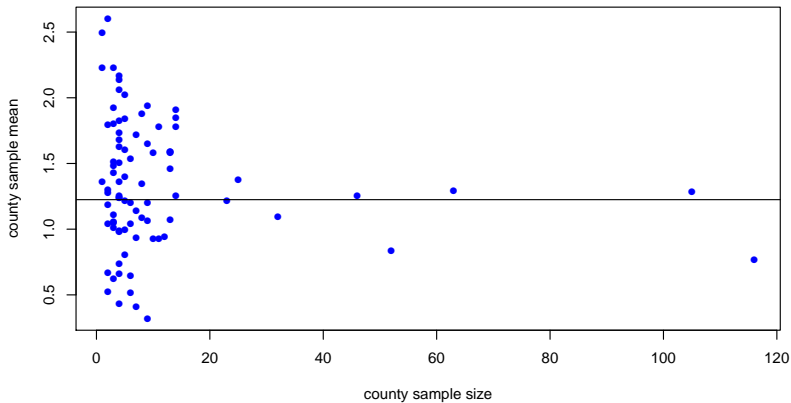
## Radon data

Log radon levels of 85 Minnesota counties.

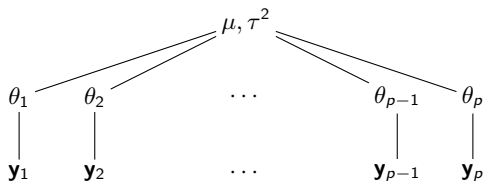




## Varying variability



## Hierarchical normal model:

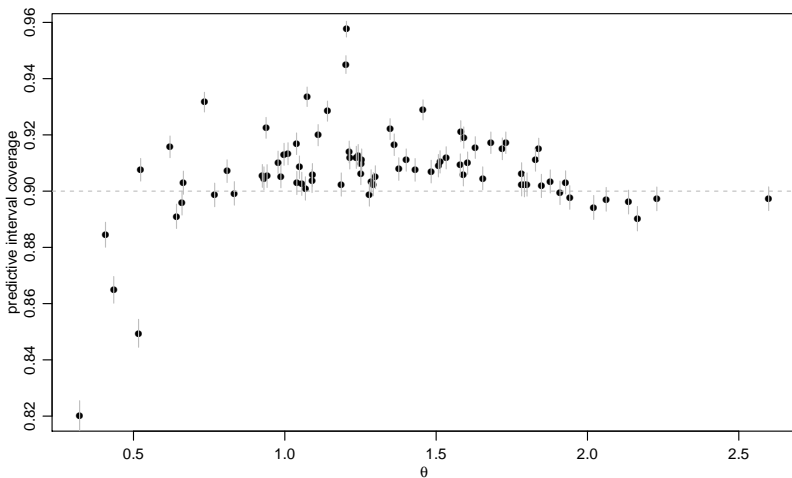


$$y_{1,j}, \dots, y_{n_j,j} \sim \text{i.i.d. } N(\theta_j, \sigma^2)$$

$$\theta_1, \dots, \theta_p \sim \text{i.i.d. } N(\mu, \tau^2)$$



## Nonconstant credible interval coverage



$$\Pr(\theta_j \in C(\hat{\theta}_j)) \approx 1 - \alpha$$

$$\Pr(\theta_j \in C(\hat{\theta}_j) | \theta_j) \text{ depends on } \theta_j.$$

## Empirical Bayes prior

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Has  $1 - \alpha$  constant coverage if

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**Adaptive inference:** Obtain  $\tilde{s}$  from groups other than  $j$

- Group sample variances provide independent estimates of  $\sigma^2$ :  $\hat{\sigma}^2, \tilde{\sigma}^2$ ;
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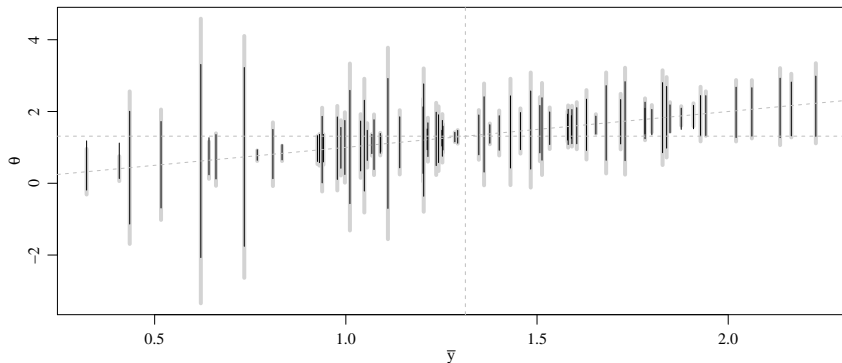
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## Radon intervals



- FAB narrower than UMAU for 77 out of 82 counties.
- Average width ratio is 0.77.

## Asymptotic optimality

Under the hierarchical normal model, the oracle CIP for  $\theta_j$  is

$$C_s^j(\mathbf{y}) = \{\theta : \bar{y}_j + n_j^{-1/2} \sigma z_{\alpha(1-s(\theta))} < \theta < \bar{y}_j + n_j^{-1/2} \sigma z_{1-\alpha s(\theta)}\}$$

Our adaptive CIP for  $\theta_j$  is

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As  $p \rightarrow \infty$ , almost surely we have

$$(\tilde{\mu}, \tilde{\tau}^2, \tilde{\sigma}^2, \hat{\sigma}^2) \rightarrow (\mu, \tau^2, \sigma^2, \sigma^2)$$

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$$t_\gamma \rightarrow z_\gamma$$

$$C_{\tilde{s}}^j(\mathbf{y}) \rightarrow C_s^j(\mathbf{y})$$

- coverage rate is exact, constant, non-asymptotic;
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$$t_\gamma \rightarrow z_\gamma$$

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Tensor data and models

FAB tests and CIs

AFAB tests and CIs

Multilevel data

**Linear regression**

Tensor parameters

## FAB intervals for regression coefficients

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y} \sim N_p(\boldsymbol{\beta}, \sigma^2 (\mathbf{X}^\top \mathbf{X})^{-1})$$

$$\hat{\sigma}^2 = \|\mathbf{y} - \mathbf{X}\hat{\boldsymbol{\beta}}\|^2 / (n - p) \sim \frac{\sigma^2}{n-p} \chi_{n-p}^2$$

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- $\hat{\beta}_j, \hat{\sigma}, \tilde{s}$  independent;
- $(n - p)\hat{\sigma}^2 / \sigma^2 \sim \chi_{n-p}^2$ ;
- $\tilde{s}$  an estimate of Bayes-optimal  $s$ -function under the prior

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## Independent pieces

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \sigma\boldsymbol{\epsilon}$$

- $\mathbf{P}_X = \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top$
- $\mathbf{P}_0 = \mathbf{I} - \mathbf{P}_X$
- $\mathbf{P}_1 = \mathbf{a}\mathbf{a}^\top / \mathbf{a}^\top \mathbf{a}$ , where  $\hat{\beta}_j = \mathbf{a}^\top \mathbf{y}$
- $\mathbf{P}_2 = \mathbf{P}_X(\mathbf{I} - \mathbf{P}_1)$ .

$$\begin{aligned} \mathbf{y} = \mathbf{I}\mathbf{y} &= (\mathbf{P}_0 + \mathbf{P}_X)\mathbf{y} \\ &= (\mathbf{P}_0 + \mathbf{P}_1 + \mathbf{P}_2)\mathbf{y} \\ &= \mathbf{P}_0\mathbf{y} + \mathbf{P}_1\mathbf{y} + \mathbf{P}_2\mathbf{y} \equiv \mathbf{y}_0 + \mathbf{y}_1 + \mathbf{y}_2. \end{aligned}$$

Get independent estimates of

- $\sigma^2$  from  $\mathbf{y}_0$ ,
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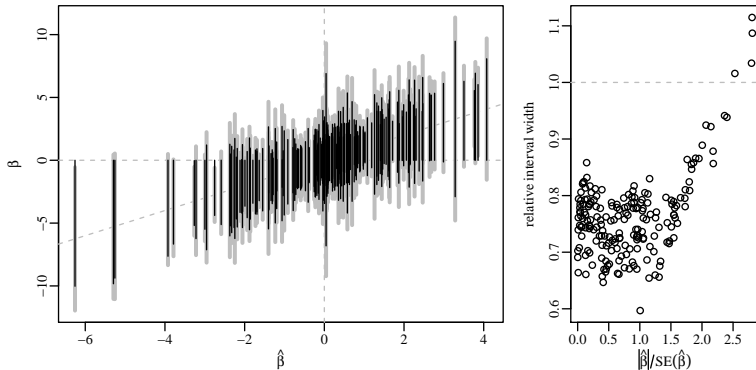
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## Motif binding

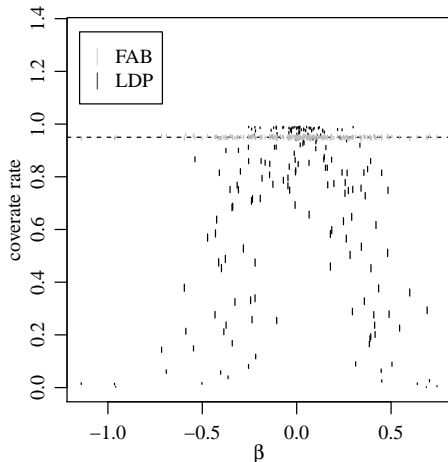
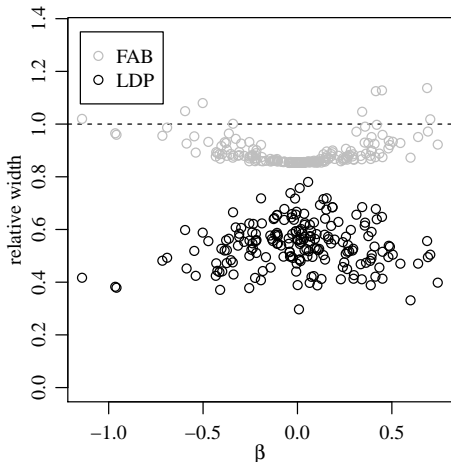
Conlon(2003) related protein binding intensity of  $n = 287$  DNA segments to abundance of  $p = 195$  genetic motifs.



- FAB intervals shorter than UMAU for 191 of 195 coefficients;
- relative widths ranging between 0.60 to 1.11, 0.76 on average.

## Another adaptive procedure

Zhang and Zhang (2014) develop an adaptive CIP for sparse situations.



Coverage of LDP achieves nominal rate

- asymptotically;
- if certain sparsity conditions are met.

## Asymptotic optimality

**Intuition:** If  $n$  and  $p$  are large then

- $(\hat{\sigma}, \tilde{\sigma}, \tilde{\tau}) \approx (\sigma, \sigma, \tau)$ ,
- $\tilde{s} \approx s$
- $z_{1-\alpha/2} \approx t_{1-\alpha/2}$ ,

and so we expect  $C_{\tilde{s}} \approx C_s$ .

**Theorem:** If as  $n \rightarrow \infty$

- $p/n \rightarrow c \in (0, 1)$ ;
- $\sigma^2/n \rightarrow \sigma_0^2$ ;
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then

- $(\hat{\sigma}/n, \tilde{\sigma}/n, \tilde{\tau}) \xrightarrow{P} (\sigma_0, \sigma_0, \tau^2)$
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Tensor data and models

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**Tensor parameters**

## Tensor data analysis

*Use tensor shape to assist with estimation and inference.*

**Tensor models:** Assume  $\Theta$  is low dimensional

- $\text{vec}(\Theta) = \mathbf{C} \otimes \mathbf{B} \otimes \mathbf{A}$ ;
- $\Theta$  is low matrix or tensor rank;
- $\Theta$  has other structure (e.g. spatial).

**Goal:** CIs, tests for elements of  $\Theta$  that

- are valid if tensor model is incorrect;
- adapt to tensor model if correct.

**Method:** Use structured tensor model as a working model for FAB.

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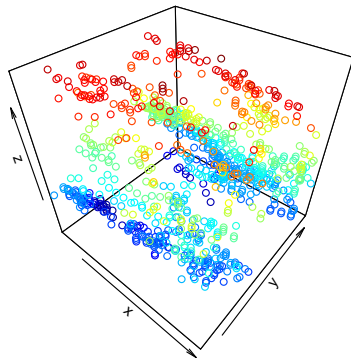
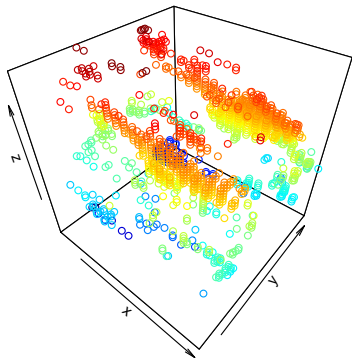
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## Spatially adaptive FAB

**DTI data** (Deutsch et al. (2005), Efron (2010)):

- 3d brain images of 6 dyslexic and 6 non-dyslexic children;
- $p = 15,443$  voxel measurements from a  $73 \times 55 \times 20$  grid;
- z-score from a two-sample  $t$ -test at each voxel.



## Spatially adaptive FAB

### Statistical model:

$$\mathbf{Y} = \Theta + \mathbf{Z}$$

### Working model for adaptation:

$$\theta_i | \Theta_{-i} \sim N(\gamma \times \sum_{i' \sim i} \theta_{i'}, \tau^2)$$

**FAB CI/test:** Is a value  $\theta$  in the CI for  $\theta_i$ ? Do a level  $\alpha$  test of

$$H : y_i \sim N(\theta, 1)$$

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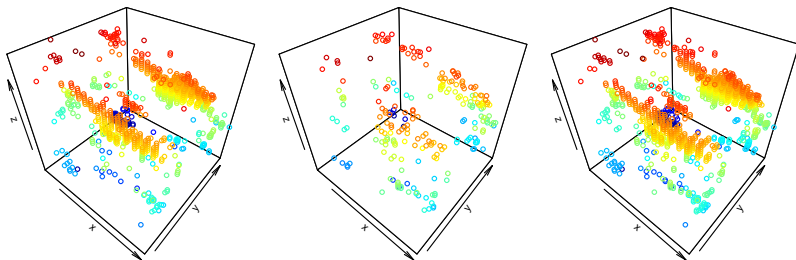
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- 229 additional voxels significant ( $\alpha = .05$ ), all with positive  $y_i$  values;
- 3 voxels no longer significant.

## Adapting to multilinear tensor regression

**Data:**  $\mathbf{y}_t = \text{vec}(\mathbf{Y}_t) \in \mathbb{R}^{p_1 p_2}$ ,  $\mathbf{x}_t = \text{vec}(\mathbf{X}_t) \in \mathbb{R}^{q_1 q_2}$

**Full model:**  $\Theta \in \mathbb{R}^{p_1 p_2 \times q_1 q_2}$

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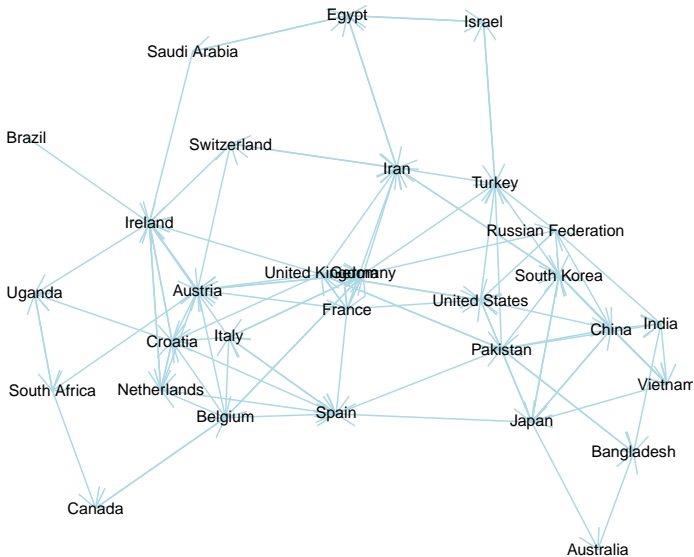
## FAB approach

**F.A.B.** : For a given dyad  $(i, j)$ ,

1. obtain OLS estimate  $\hat{\theta}_{ij}$  and its SE with  $\{y_{i,j,t}\}$ ;
2. obtain  $\hat{\mathbf{a}}_i, \hat{\mathbf{a}}_j$  of working model without  $\{y_{i,j,t}\}$ ;
3. evaluate elements of  $\theta_{ij}$  using tests with power near  $\theta_{i,j} = \mathbf{a}_i \otimes \mathbf{a}_j$ .



## Adapt to this



## Results

**Some results:** Testing at  $\alpha = .05 / \binom{p}{2}$ ,

- FAB identifies 13% more dyads as having significant influence;
- FAB-identified effects make more intuitive sense.

**Some caveats:**

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## References

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