

Shifted Laplace and related preconditioning for the Helmholtz equation

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Collaborations with:

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Outline of talk:

- seismic imaging (**Schlumberger Gould Research**)
 - high-frequency Helmholtz, variable wave speed
 - Conventional FE discretization, **efficient solvers?**
 - Iterative method: GMRES **convergence rates?**
 - preconditioners based on absorption
 - brief summary of mathematical results
 - numerical experiments
-

Chandler-Wilde, IGG, Langdon, Spence Acta Numerica 2012:
Numerical-asymptotic boundary integral methods in
high-frequency scattering

See also Dave Hewett's talk

3. "very cost" 4. "K. O."

Marine seismic



Seismic Towing Configuration

1991
Outer Separators: 1300 m
Streamer length: 5000 m
Revolving Driftstar

Schlumberger

Photo: Schlumberger - Wilmann AG

Seismic inversion

Inverse problem: reconstruct material properties of subsurface (characterised by wave speed $c(x)$) from observed echos.

Regularised iterative method: repeated solution of the (forward problem): the wave equation

$$-\Delta u + \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = f \quad \text{or its elastic variant}$$

Frequency domain:

$$-\Delta u - \left(\frac{\omega}{c}\right)^2 u = f, \quad \omega = \text{frequency}$$

solve for u with approximate c .

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Frequency domain:

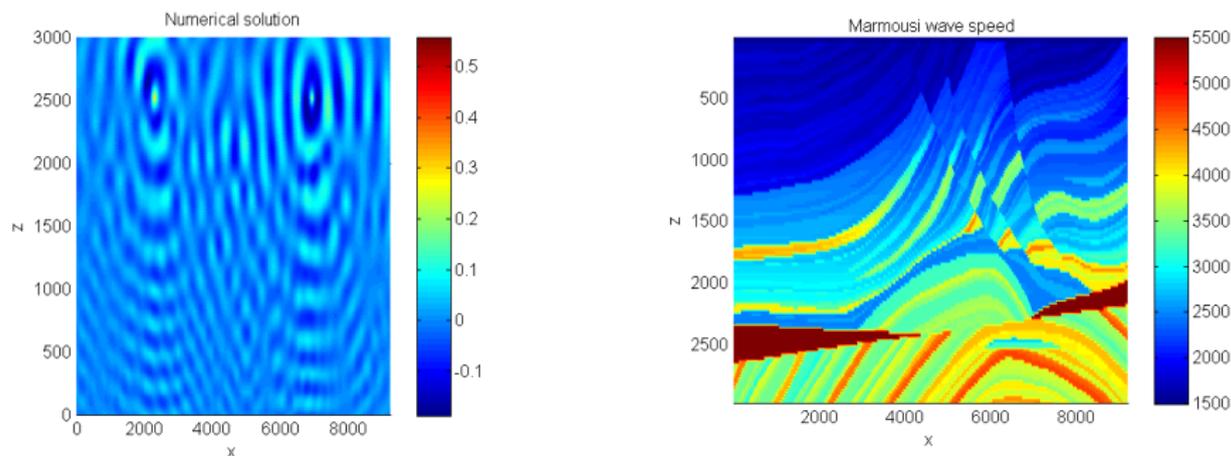
$$-\Delta u - \left(\frac{\omega L}{c}\right)^2 u = f, \quad \omega = \text{frequency}$$

solve for u with approximate c .

Large domain of characteristic length L .

effectively high frequency

Marmousi Model Problem

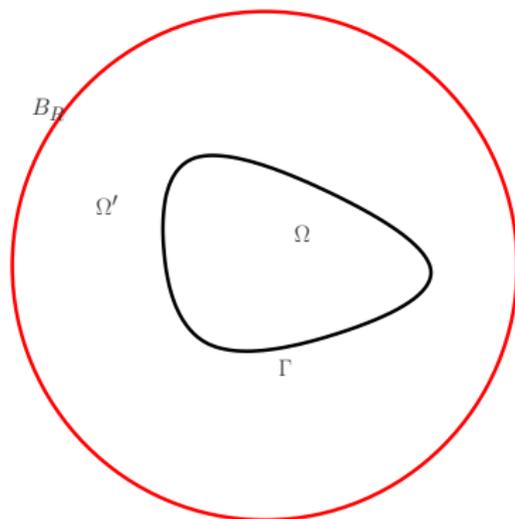


- **Time domain**: explicit finite difference methods (slow)
- **Frequency domain**: large linear systems for each ω
- Solver of choice (2007) based on principle of limited absorption (Erlangga, Osterlee, Vuik, 2004)...
- This work: develop better solvers, (parallel algorithms?)

Model interior impedance problem

$$\begin{aligned} -\Delta u - k^2 u &= f \quad \text{in bounded domain } \Omega \\ \frac{\partial u}{\partial n} - iku &= g \quad \text{on } \Gamma := \partial\Omega \end{aligned}$$

Results all hold for truncated sound-soft scattering problems in Ω' (large R)



Linear algebra problem

- weak form

$$\begin{aligned} a(u, v) &:= \int_{\Omega} (\nabla u \cdot \nabla \bar{v} - k^2 u \bar{v}) - ik \int_{\Gamma} u \bar{v} \\ &= \int_{\Omega} f \bar{v} + \int_{\Gamma} g \bar{v} \end{aligned}$$

- finite element discretization

$$\mathbf{A} \mathbf{u} := (\mathbf{S} - k^2 \mathbf{M}^{\Omega} - ik \mathbf{M}^{\Gamma}) \mathbf{u} = \mathbf{f}$$

Often: $h \sim k^{-1}$ **but pollution effect:**
need $h \sim k^{-2} ??$, $h \sim k^{-3/2} ??$

Less dispersion: higher order FD or FE methods

Linear algebra problem

- weak form **with absorption** $k^2 \rightarrow k^2 + i\varepsilon$,

$$\begin{aligned} a_\varepsilon(u, v) &:= \int_{\Omega} (\nabla u \cdot \nabla \bar{v} - (k^2 + i\varepsilon)u\bar{v}) - ik \int_{\Gamma} u\bar{v} \\ &= \int_{\Omega} f\bar{v} + \int_{\Gamma} g\bar{v} \quad \text{“Shifted Laplacian”} \end{aligned}$$

[Equivalently $k^2 + i\varepsilon \longleftrightarrow (k + i\rho)^2$]

- Finite element discretization

$$\mathbf{A}_\varepsilon \mathbf{u} := (\mathbf{S} - (k^2 + i\varepsilon)\mathbf{M}^\Omega - ik\mathbf{M}^\Gamma)\mathbf{u} = \mathbf{f}$$

A_ε somehow **“better behaved”** than A .

How bad things can be $\varepsilon = 0$

Solving $\mathbf{Ax} = \mathbf{f} = \mathbf{1}$ on unit square $h \sim k^{-3/2}$

Using GMRES

(minimises residual in Krylov space: $\text{span}\{\mathbf{f}, \mathbf{A}\mathbf{f}, \dots, \mathbf{A}^{k-1}\mathbf{f}\}$)

k	n	# GMRES
25	15876	467
30	22801	633
35	44521	966
40	58081	> 1000

Preconditioning with \mathbf{A}_ϵ^{-1}

Solve instead:

$$\mathbf{A}_\epsilon^{-1} \mathbf{A} \mathbf{u} = \mathbf{A}_\epsilon^{-1} \mathbf{f}.$$

Theorem (with Martin Gander and Euan Spence)

For Lipschitz star-shaped domains:

If ϵ/k is sufficiently small then GMRES converges independent of k .

Proof: uses (high frequency) analysis of continuous problem.

Warning: not a practical method (yet!)

Shifted Laplacian preconditioner $\varepsilon = k$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

	k	# GMRES
	10	6
$h \sim k^{-3/2}$	20	6
	40	6
	80	6

Shifted Laplacian preconditioner $\varepsilon = k^{3/2}$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

	k	# GMRES
	10	8
$h \sim k^{-3/2}$	20	11
	40	14
	80	16

Shifted Laplacian preconditioner $\varepsilon = k^2$

Solving $\mathbf{A}_\varepsilon^{-1} \mathbf{A} \mathbf{x} = \mathbf{A}_\varepsilon^{-1} \mathbf{1}$ on unit square

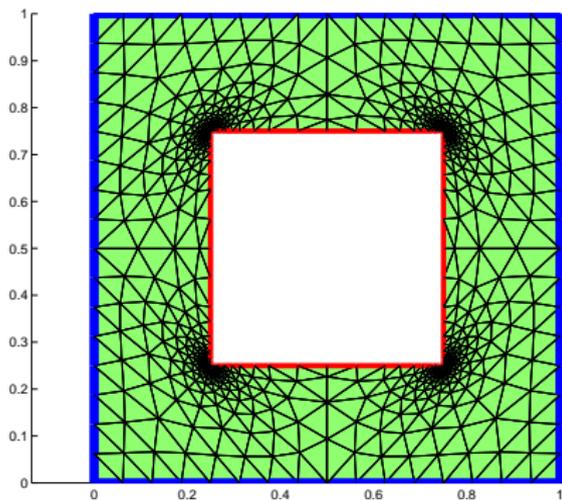
	k	# GMRES
	10	13
$h \sim k^{-3/2}$	20	24
	40	48
	80	86

Exterior scattering problem with refinement

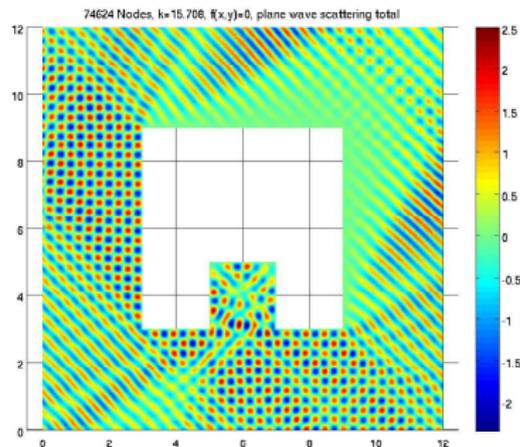
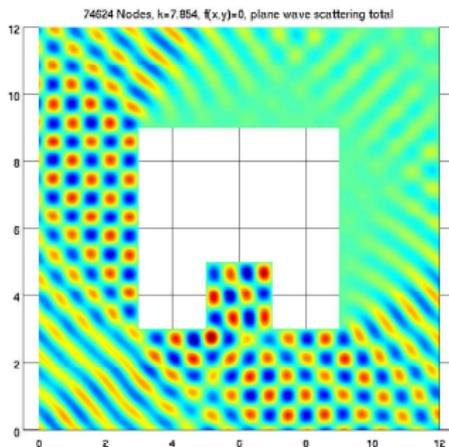
$$h \sim k^{-1}, \quad \# \text{ GMRES}$$

with diagonal scaling

k	$\varepsilon = k$	$\varepsilon = k^{3/2}$
20	5	8
40	5	11
80	5	13
160	5	16



A trapping domain



k	$\epsilon = k$	$\epsilon = k^{3/2}$
$10\pi/8$	18	29
$20\pi/8$	19	41
$40\pi/8$	21	60
$80\pi/8$	22	89

Betcke, Chandler-Wilde, IGG, Langdon, Lindner, 2010

Part II: Domain decomposition for A_ε^{-1}

Approximate by solves with A_ε in subspaces:

subdomains

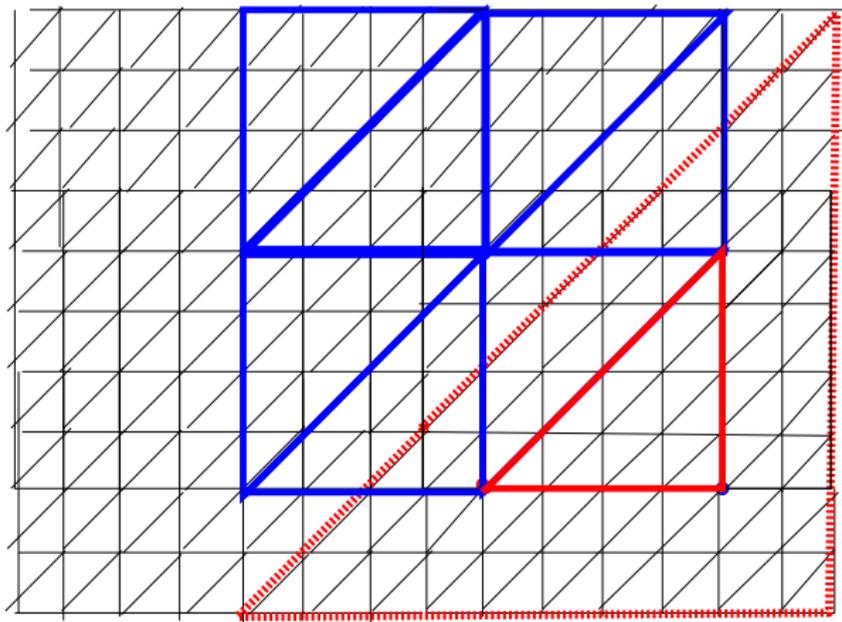
coarse grid

Questions: Convergence, Scalability?

Classical additive Schwarz

To solve a problem on a fine grid FE space \mathcal{S}_h

- **Coarse space** \mathcal{S}_H (here linear FE) **on a coarse grid**
- **Subdomain spaces** \mathcal{S}_i **on subdomains** Ω_i , overlap δ



Approximation of C^{-1} :

$$\sum_i \mathbf{R}_i^T \mathbf{C}_i^{-1} \mathbf{R}_i + \mathbf{R}_H^T \mathbf{C}_H^{-1} \mathbf{R}_H$$

\mathbf{R}_i = restriction to S_i , \mathbf{R}_H = restriction to S_H
 $\mathbf{C}_i = \mathbf{R}_i \mathbf{C} \mathbf{R}_i^T$ $\mathbf{C}_H = \mathbf{R}_H \mathbf{C} \mathbf{R}_H^T$

Apply to A_ε to get B_ε^{-1}

Convergence results (work in progress)

Theorem IGG, E. Spence, E. Vainikko, 2014

Consider solving

$$B_\varepsilon^{-1} A_\varepsilon \mathbf{x} = B_\varepsilon^{-1} \mathbf{f}$$

n = number of GMRES iterates to achieve fixed accuracy

$$n \sim \left(\frac{k^2}{\varepsilon} \right)^4$$

provided $kH \leq c \left(\frac{\varepsilon}{k^2} \right)^{3/2}$

So $\varepsilon \sim k^2 \implies$ **robust method no pollution in coarse grid.**

Actually we want to solve

$$B_\varepsilon^{-1} A \mathbf{x} = B_\varepsilon^{-1} \mathbf{f} \quad \varepsilon \sim k^2$$

Numerical experiments: unit square, impedance BC

B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

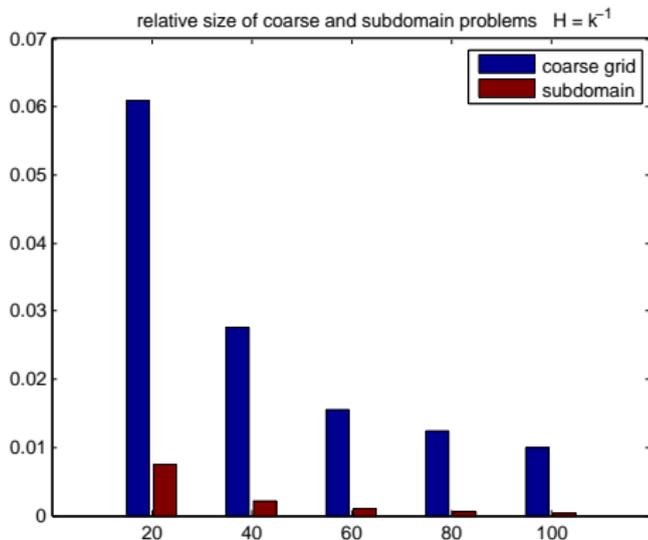
$$h \sim k^{-3/2},$$

$$kH \sim 1$$

Relative **Coarse** and **subdomain** problem size

Scale = 0.07

k	#GMRES
20	8
40	8
60	8
80	8
100	8



B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

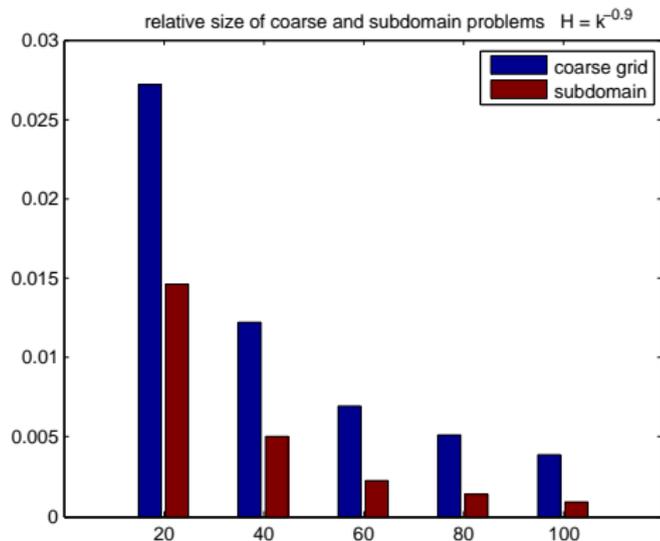
$$h \sim k^{-3/2},$$

$$kH \sim k^{0.1}$$

Relative **Coarse** and **subdomain** problem size

Scale = 0.03

k	#GMRES
20	9
40	10
60	10
80	10
100	10



B_ε^{-1} as preconditioner for A_ε $\varepsilon = k^2$

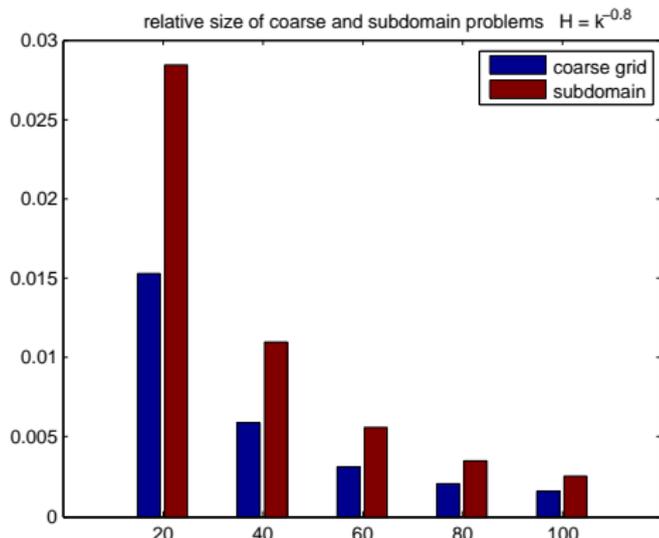
$$h \sim k^{-3/2},$$

$$kH \sim k^{0.2}$$

Relative **Coarse** and **subdomain** problem size

Scale = 0.03

k	#GMRES
20	10
40	10
60	11
80	11
100	11



“Aggressive coarseing”

B_ε^{-1} as preconditioner for A_ε and A $\varepsilon = k$

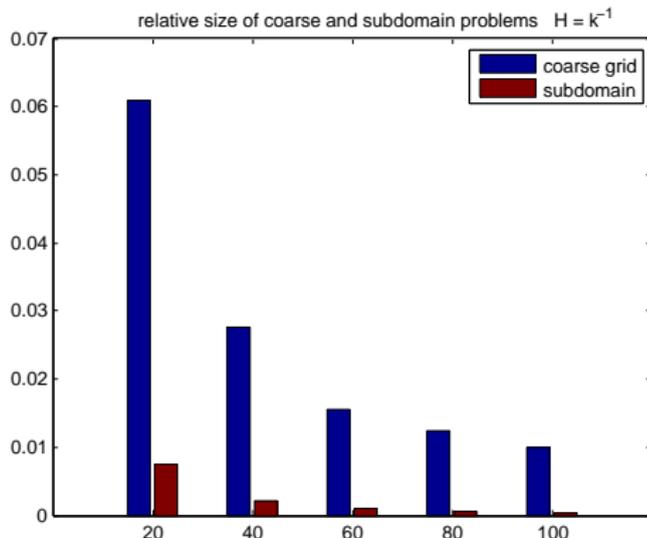
$$h \sim k^{-3/2},$$

$$kH \sim 1$$

Relative **Coarse** and
subdomain problem size

Scale = 0.07

k	for A_ε	for A
20	11	12
40	14	15
60	19	20
80	24	26
100	31	33



When $\varepsilon \sim k$

Introduce more “wavelike” components:

Impedance boundary condition on subdomains

Hybrid restricted additive Schwarz

B_ε^{-1} as preconditioner for A $\varepsilon = k$

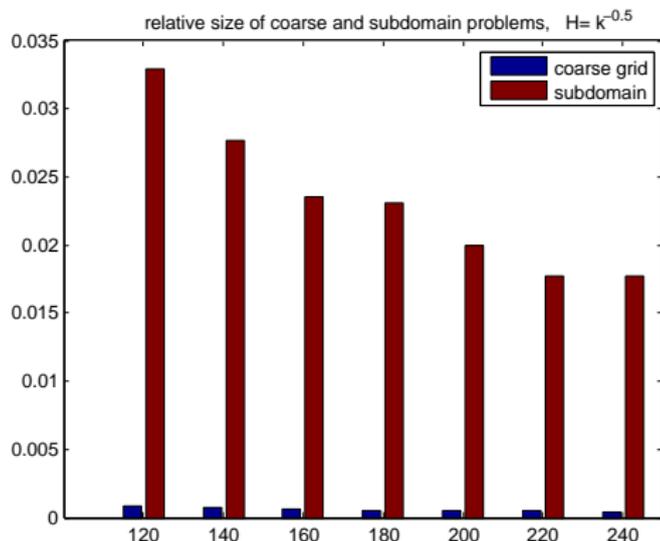
20 grid points per wavelength, Hybrid RAS,
Impedance subdomain problems

$$kH \sim k^{0.5}$$

Relative **Coarse** and
subdomain problem size

Scale = 0.035

k	#GMRES
120	51
140	56
160	59
180	57
200	61
220	64
240	65



Complexity (serial): $\sim n \log n$, $h \gtrsim 10^{-10}$ in 2D

B_ε^{-1} as preconditioner for A $\varepsilon = k$

20 grid points per wavelength, Hybrid RAS, $kH \sim k^{0.5}$

k	GMRES , impedance	GMRES , Dirichlet
120	51	487
140	56	595
160	59	> 600
180	57	> 600

Summary

- k and ϵ explicit analysis allows **rigorous explanation** of some empirical observations and formulation of new methods.
- When $\epsilon \sim k$, \mathbf{A}_ϵ^{-1} is optimal preconditioner for \mathbf{A}
- When $\epsilon \sim k^2$, \mathbf{B}_ϵ^{-1} is optimal preconditioner for \mathbf{A}_ϵ
- When preconditioning \mathbf{A} with \mathbf{B}_ϵ^{-1} , **best choice is $\epsilon \sim k$**
- Then BC of subdomain problems very important (impedance, PML,...).
- **New analysis** of Domain Decomposition methods.