Reconstruction of a perfectly conducting obstacle coated with a thin dielectric layer

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The scattering problem for coated obstacles in the harmonic regime



The inverse scattering problem for coated obstacles



Qualitative techniques

+ Fast

- Need a lot of data
- Not very accurate

Quantitative techniques

- + Provide accurate reconstruction
- Need a priori information

- Computational cost

Design an optimization procedure to find the shape and the thickness from scattered field data.

Outline

Formulation of the inverse problem
An optimization point of view
A GIBC approximate model

2 Derivatives of the cost function



The inverse problem

 $\underline{ \text{The far field map}}_{T^{\text{coat}}} \text{ For } u^i(x, \hat{\theta}) = e^{ik\hat{\theta}\cdot x} \text{ define}$ $T^{\text{coat}} : (\epsilon, \mu, \delta, \Gamma, \hat{\theta}) \mapsto u^{\infty}(\hat{x}, \hat{\theta})$

where u^{∞} associated with u^s is defined in dimension d by

$$u^{s}(x) = \frac{e^{ikr}}{r^{(d-1)/2}} \left(u^{\infty}(\hat{x}) + \mathcal{O}\left(\frac{1}{r}\right) \right) \qquad r \longrightarrow +\infty.$$

The inverse problem

Given N far-fields $(u_{\text{coat}}^{\infty}(\cdot, \hat{\theta}_j))_{j=1,\dots,N}$, retrieve the geometry Γ and the properties of the layer.

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Minimize

$$\overline{F^{\text{coat}}}(\epsilon,\mu,\delta,\Gamma) := \frac{1}{2} \sum_{j=1}^{N} \|T^{\text{coat}}(\epsilon,\mu,\delta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{coat}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}$$



 T^{coat} is computationally expensive to evaluate!

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$$\underbrace{\frac{\text{Minimize}}{F^{equi}(\epsilon,\mu,\delta,\Gamma)}}_{F^{equi}(\epsilon,\mu,\delta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{coat}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}}$$

An approximate GIBC model



In dimension 2: (Aslanyüreck, Haddar, Şahintürk [11])

$$\mathbf{Z}_1 = \frac{\partial}{\partial s} \delta \epsilon^{-1} \frac{\partial}{\partial s} + \delta k^2 \mu$$
$$\mathbf{Z}_2 = \frac{\partial}{\partial s} \left(\delta - \frac{\delta^2 c}{2} \right) \epsilon^{-1} \frac{\partial}{\partial s} + \left(\delta + \frac{\delta^2 c}{2} \right) k^2 \mu.$$

The GIBC forward problem

Find $u = u^s + u^i$ such that

$$u^{s} \in \left\{ v \in \mathcal{D}'(\Omega_{\text{ext}}), \ \varphi v \in H^{1}(\Omega_{\text{ext}}) \ \forall \varphi \in \mathcal{D}(\mathbb{R}^{d}); \ v_{|\Gamma} \in H^{1}(\Gamma) \right\}$$

and

$$(\mathcal{P}) \begin{cases} \Delta u + k^2 u = 0 \quad \text{in } \Omega_{\text{ext}} \\ \frac{\partial u}{\partial \nu} + \operatorname{div}_{\Gamma}(\eta \nabla_{\Gamma} u) + \lambda u = 0 \quad \text{on } \Gamma \\ \lim_{R \to \infty} \int_{|x|=R} \left| \frac{\partial u^s}{\partial r} - iku^s \right|^2 ds = 0. \end{cases}$$

u exists and is unique if

Sm(λ) ≥ 0, Sm(η) ≤ 0 a.e. on Γ (physical assumption)
ℜe(η) ≥ c a.e. on Γ for c > 0.

Reformulation of the inverse problem

 $\frac{\text{The far field map for the GIBC model}}{\text{For } u^i(x, \hat{\theta}) = e^{ik\hat{\theta}\cdot x} \text{ define}}$

$$T^{GIBC}: (\lambda, \eta, \Gamma, \hat{\theta}) \mapsto u^{\infty}(\hat{x}, \hat{\theta}).$$

For thin layer we have:

$$T^{GIBC}(\delta k^2 \mu, \delta \epsilon^{-1}, \Gamma, \hat{\theta}_j) = T^{\text{coat}}(\epsilon, \mu, \delta, \Gamma, \hat{\theta}_j) + \mathcal{O}(\delta^{3/2})$$

New functional to minimize

Given N far–fields $(u_{\text{coat}}^{\infty}(\cdot,\hat{\theta}_j))_{j=1,\cdots,N}$ corresponding to the coated obstacle, minimize

$$F^{GIBC}(\lambda,\eta,\Gamma) := \frac{1}{2} \sum_{j=1}^{N} \|T^{GIBC}(\lambda,\eta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{coat}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}$$

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Difficulty related to the shape derivative

$$\label{eq:GIBC model: } \text{GIBC model: } \frac{\partial u}{\partial \nu} + \text{div}_{\Gamma}(\eta \nabla_{\Gamma} u) + \lambda u = 0 \quad \text{on } \Gamma$$

$$F^{GIBC}(\lambda,\eta,\Gamma) := \frac{1}{2} \sum_{j=1}^{I} \|T^{GIBC}(\lambda,\eta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{coat}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}$$

For minimizing F^{GIBC} we use a steepest descent method:

- we need partial derivatives of the far–field with respect to λ and η (quite standard),
- we need an appropriate derivative w.r.t. the obstacle.



Difficulty: the unknown impedances are supported by Γ .

Derivative of the cost function with respect to the obstacle



 $h \in C^{1,\infty}(\mathbb{R}^d, \mathbb{R}^d)$ is "small" $f_h := \mathrm{Id} + h$ $\Gamma_h := f_h(\Gamma)$ λ and η being constant

We define the derivative v_h of the scattered field with respect to the geometry at point (λ, η, Γ) by

$$u^{s}(\lambda,\eta,\Gamma_{h}) - u^{s}(\lambda,\eta,\Gamma) = v_{h} + o(||h||)$$

where $h \mapsto v_h$ is linear.

Derivative of the cost function with respect to the obstacle



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where $h \mapsto v_h$ is linear.

One may find f_h such that $\Gamma = f_h(\Gamma)$ and

$$F'_{\lambda,\eta}(\Gamma) \cdot h \neq 0.$$



 $F'_{\lambda,\eta}(\Gamma)$ does not satisfy the classical shape derivative's properties!

Derivative of the scattered field with respect to the obstacle

Let (λ,η,Γ) be given and analytic, for some small $h\in C^{1,\infty}$ define

$$\Gamma_h = f_h(\Gamma), \quad \lambda_h := \lambda \circ f_h^{-1} \text{ and } \eta_h := \eta \circ f_h^{-1}.$$

Let $u_h^s [u^s]$ be scattered field associated with $(\lambda_h, \eta_h, \Gamma_h) [(\lambda, \eta, \Gamma)]$.

$$u_h^s(x) - u^s(x) = v_h(x) + o(||h||),$$

where $v_h(x)$ is the solution of the scattering problem with

$$\begin{aligned} \frac{\partial v_h}{\partial \nu} + \mathbf{Z} v_h &= B_h u \quad \text{on} \quad \Gamma \\ B_h u &= (h \cdot \nu) (k^2 - 2H\lambda) u + \operatorname{div}_{\Gamma} ((Id + 2\eta (R - H Id))(h \cdot \nu) \nabla_{\Gamma} u) \\ &+ (\nabla_{\Gamma} \lambda \cdot h) u + \operatorname{div}_{\Gamma} ((\nabla_{\Gamma} \eta \cdot h) \nabla_{\Gamma} u) \\ &+ \mathbf{Z} ((h \cdot \nu) \mathbf{Z} u) \,, \end{aligned}$$

with
$$2H := \operatorname{div}_{\Gamma} \nu$$
, $R := \nabla_{\Gamma} \nu$ and $\mathbf{Z} \cdot = \operatorname{div}_{\Gamma}(\eta \nabla_{\Gamma} \cdot) + \lambda \cdot$

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Numerical algorithm



$$F^{\text{GIBC}}(\lambda,\eta,\Gamma) := \frac{1}{2} \sum_{j=1}^{I} \|T^{\text{GIBC}}(\lambda,\eta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{obs}}(\cdot,\hat{\theta}_j)\|_{L^2(S_j)}^2$$

Numerical procedure:

• update alternatively λ , η and Γ with a direction given by the partial derivative of the cost function,

$$\lambda^{\mathsf{n}+1} = \lambda^{\mathsf{n}} - \alpha_{\mathsf{n}} \mathsf{F}'_{\eta, \mathsf{\Gamma}}(\lambda^{\mathsf{n}})$$

The regularization procedure

$$F^{\text{GIBC}}(\lambda,\eta,\Gamma) = \frac{1}{2} \sum_{j=1}^{I} \|T^{\text{GIBC}}(\lambda,\eta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{obs}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}$$

We regularize the gradient, NOT the cost function, using a $H^1(\Gamma)$ regularization.

▶ Descent direction for λ : find $\delta\lambda$ that solves for every ϕ in some finite dimensional space:

$$\beta_{\lambda} \int_{\Gamma} \nabla_{\Gamma}(\delta \lambda) \cdot \nabla_{\Gamma} \phi \, ds + \int_{\Gamma} \delta \lambda \phi \, ds = -\alpha_{\lambda} \, F_{\eta,\Gamma}'(\lambda) \cdot \phi$$

where β_{λ} is the regularization coefficient and α_{λ} is the descent coefficient.

▶ Do the same for $\delta\eta$ and $\delta\Gamma$.

Numerical reconstruction

Finite elements method and remeshing procedure $using \ FreeFem++$



Reconstruction of the geometry with 2 incident waves and 1% noise on the far-field, $\lambda = ik/2$ and $\eta = 2/k$ being known. The synthetic data come from the GIBC model

Application to the reconstruction of a coated obstacle



Reconstruction of an obstacle using the generalized impedance boundary condition model of order 1 minimizing

$$F^{GIBC}(\mu,\delta,\Gamma) := \frac{1}{2} \sum_{j=1}^{I} \|T^{GIBC}(\mu,\delta,\Gamma,\hat{\theta}_j) - u^{\infty}_{\text{coat}}(\cdot,\hat{\theta}_j)\|^2_{L^2(S_j)}$$

with $\epsilon = 0.1$ known.

Application to the reconstruction of a coated obstacle

Numerical results

Artificial data created with

- $\epsilon = 0.1$ is known,
- $\delta = 0.04l(1 0.4\sin(\theta))$ is unknown; *l* being the wavelength,
- $\mu = 2.5$ is unknown.

Reconstructed μ : 2.3.



Fails with a classical impedance boundary condition model!

Conclusion

- ▶ The quantitative reconstruction of coated obstacles can be quite fast and accurate.
- ▶ The optimization methods also provide the thickness of the coating as well as its physical parameters.

- \blacktriangleright Extension to the 3D Maxwell equations.
- ▶ Can be applied for any complex structure that can be approximated by a GIBC.

On simultaneous identification of a scatterer and its generalized impedance boundary condition. L. Bourgeois, N. Chaulet and H. Haddar. INRIA Research Report n 7645, 2011. Submitted